

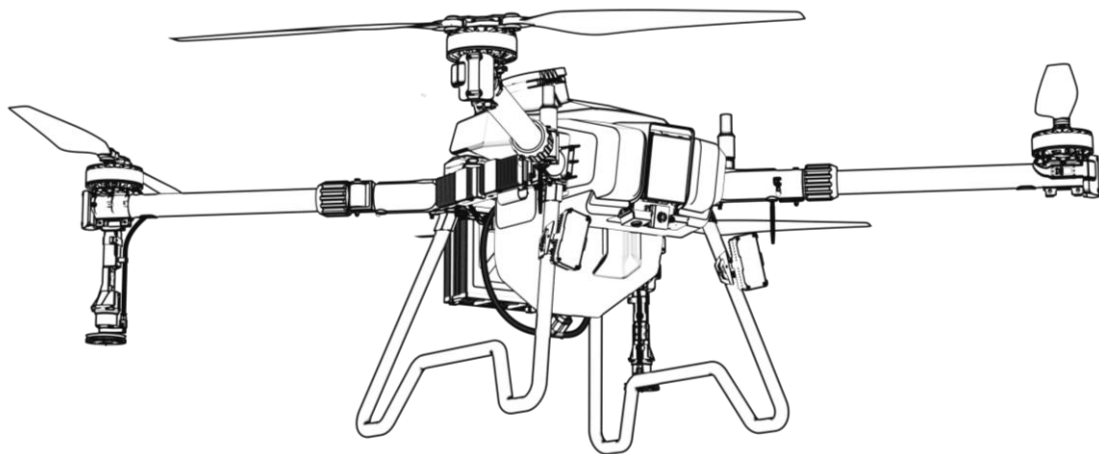


3WWDZ-U30B

Agriculture Drone

User Manual V3.0

Model: FP300E



Topxgun (Nanjing) Robotics Co., Ltd.
2025.06

Usage Recommendation

Topxgun provides user with the following documents:

1. *Packing List*
2. *3WWDZ-U30B Agriculture Drone User Manual*
3. *Agriculture Assistant APP User Manual*

For detailed usage and functions, please refer to "3WWDZ-U30B Agriculture Drone User Manual" and "Agriculture Assistant APP User Manual". You can also follow us on YouTube Channel for tutorials and tips in the operation.

* To keep you updated, some documents may be taken as E-documents.



Preface

The 3WWDZ-U30B agricultural drone is a mature multi-rotor UAV, leading the industry

in terms of function, appearance, control, safety and other aspects. There are certain usage risks of multi-rotor drones due to the mechanism and structure. Please strictly follow the safety tips and user manual during the operation. Improper use of this product may result in direct or indirect losses and injuries.

Disclaimer

Please read the manual carefully before using the aircraft. Once the drone is used, it is deemed to be an acknowledgement and acceptance of all the content of this user manual. This drone is suitable for people 18 years of age and older. Topxgun is not responsible for the loss of personal or property due to the following problems:

1. The user does not assemble or use the drone as required by this manual.
2. The user operates the drone in poor physical or mental conditions such as drinking, drug abuse, fatigue, etc.
3. The user actively or intentionally operates the drone to create damage.
4. The user modifies the drone without using the accessories from Topxgun, which causes malfunction of the drone.
5. Injury caused by the user's misoperation or subjective misjudgment.
6. Damage caused by natural causes, such as aging of the circuit and so on that affects the aircraft.
7. Damage caused by the user's operation of the drone while knowing that it is in an abnormal working condition.
8. The user still operates the drone under severe weather conditions such as typhoons, hail and fog.
9. The user operates the drone in the magnetic interference area, radio interference area and government no-fly area.
10. The user operates the drone in case of poor visibility and occlusion of the line of sight.
11. The user operates the drone to cause the infringements by obtaining any data, image data and other infringement behaviors.
12. Other losses that are not within the scope of the company's liability.

Safety Operation Instructions

1. Pesticide Usage

- Wear protective clothing to prevent direct body contact with the pesticide while operating.
- Avoid the use of powder pesticides as much as possible or else they may reduce the service life of the spraying system.
- Use clean water to prepare the pesticide to avoid blocking the strainer. Do not remove any filter and clear any blockages before using the equipment.
- After using the pesticide, please clean up the residual liquid in time. It is strictly forbidden to pollute the river and drinking water source and ensure that it will not cause harm or impact on people, animals and the environment in the surroundings.
- The effect of the pesticide is closely related to the concentration of the pesticide, the spraying rate, the altitude of the drone from crops, the wind direction, the wind speed, etc. The above factors should be taken into account comprehensively when using the pesticide in order to achieve the best effect.
- Strictly follow the safety instructions of the pesticide production company.
- Particular working fluids are prohibited.
- During operations, pay attention to factors such as wind direction and pesticide toxicity, to prevent pesticide damage to adjacent plots due to mist drift.

2. Usage Environment

- Always fly in an open space, away from the crowd.
- It is recommended to fly below 2000 meters.
- It should fly in an environment with a temperature between 0°C and 40°C.
- It is recommended to fly in an environment with a wind speed below level 4.
- It is strictly forbidden to fly in rain, fog, snow or other extreme weather.
- It is strictly forbidden to fly indoors.
- It must fly in a legal area. Before flying in the legal area, please consult your local flight management department to comply with local laws and regulations.

3. Pre-flight Inspection

- Make sure that every device is fully charged.
- Make sure that all parts are in good condition. If there are some parts worn or damaged, please replace them before the flight. Make sure that the landing gear and the tank are tightly mounted and all the screws are firmly tightened.
- Make sure that the propellers are intact and firmly mounted, the propellers and arms are fully extended, and the screws are tightened.
- Make sure the motors are clean and free of damage.
- Make sure the spraying system is free of blockage and works properly.

- Please calibrate the compass before the flight.

4. Operation

- Keep away from the rotating propellers and motors.
- When folding the drone, avoid crushing and damaging the drone parts.
- Do not exceed the take-off weight to avoid danger.
- Pilots must be professionally trained and pass the assessment, and the untrained personnel must not fly the drone.
- Make sure that the propellers are removed before calibrating the drone and upgrading the firmware.
- When the drone and the remote controller are in the frequency-connecting process, make sure that the propellers are removed and that people and animals are far away from the motor.
- A pilot should not operate this product under the influence of alcohol, fatigue, illness, etc.
- If the operating environment does not meet the working condition of the radar module, the drone will not avoid obstacles when it returns automatically. If the remote-control signal is normal, the flight speed and altitude can be controlled using the remote controller.
- When working, be sure to turn on the remote controller first, and then turn on the power supply. After landing, turn off the power supply first and then turn off the remote controller.
- Please maintain control of the drone throughout the process and do not rely entirely on the information provided by the hand-held ground station(remote controller).
- Obstacle avoidance and terrain following functions will not be available in the specific flight mode or environment. Please observe the gesture of the drone at all times and judge the flight condition reasonably to avoid obstacles in time.

5. Flight Restrictions and Local Laws

- Browse the official website of the Aviation Authority of your location for the latest list of restricted flight areas.
- The maximum control flight altitude is 30 meters in China. Regulations may differ in each country, please consult the local flight management department before taking off, to comply with local laws and regulations.
- Notes: Safety operating instruction notes include but are not limited to the above items.

Intellectual Property Rights

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quoted contrary to its original intention.

About This Manual

This manual is used as a user's guide. Photos, graphics, charts and illustrations in the manual are only for explanatory and illustrative purposes and may differ from the actual product. Please refer to the actual product.

Due to product upgrades or other reasons, the content of this document will be updated from time to time. Unless otherwise agreed, it is without further notice.

Before using this product, please read this manual carefully.

Execution standard of this product: Q/TG 002-2024

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1. Product Overview

The agricultural drone 3WWDZ-U30B is mainly used for pesticide spraying, seeding, and fertilization, and has undergone multiple upgrades. It reaches the leading level in practicability, reliability and safety. The drone is full-body waterproof, dust-proof and anti-corrosion. Some key modules, such as spraying system, radar system and power system, are IP67 rated ensuring easy cleaning and maintenance. The GNSS+RTK positioning system can achieve centimeter-level high precision positioning, and also supports dual antenna anti-magnetic interference direction-finding technology. The drone is equipped with wide-angle FPV camera and high-definition digital image transmission system. Users can observe the environment in real time.

1.1. Remote Control

1.1.1. Component Definition

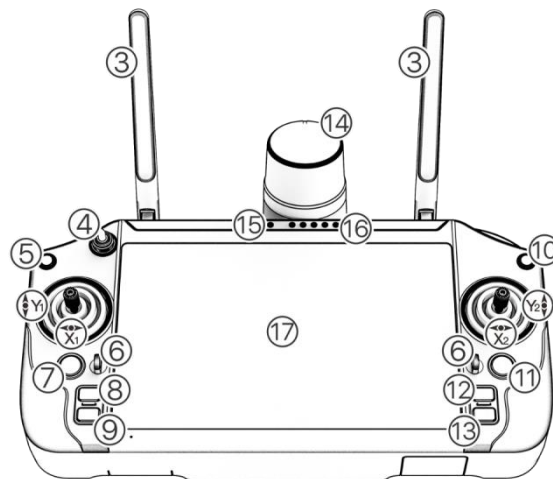


Figure 1-1

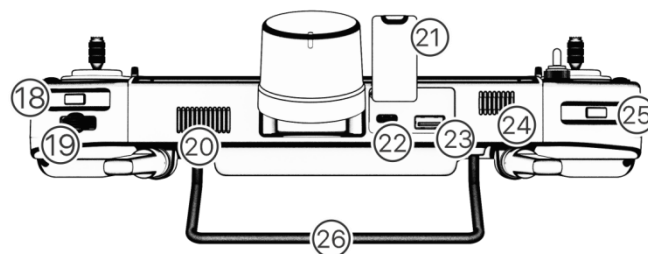


Figure 1-2



Figure 1-3

The Main Control Buttons of the Remote Control (Mode 2)			
Serial No.	Corresponding Name	Corresponding Function	Function Description
Y1	Throttle	Left stick - up and down	The drone moves vertically (up and down)
X1	Yaw	Left stick - left and right	The drone rotates (left and right)
X2	Roll	Right stick - left and right	Fly left and right
Y2	Pitch	Right stick - up and down	Fly forward and backward
3	Remote Control Antenna	Primary and auxiliary antenna	Transit the control signal, telemetry signal, telegraphic signal
4	Switch Mode Button	Toggle the switch	Switch between GPS mode and Operation mode (Turn off by default, you can turn on in Setting)
5	Return Button	Return to the previous section	Return to the previous section in the Agriculture Assistant APP
6	Hanging Holes		For lanyard attachment
7	RTH (Return-to-home) Button	Long press for 2s, the drone will return home	Long press the RTH button to activate the smart return mode
8	L1 Button	Customizable Button	Default to rudder switch button

9	L2 Button	Customizable Button	Default to obstacle avoidance radar switch button
10	Emergency Stop	Long press for 5s to lock the drone	Press for 5s to lock the drone in case of emergency
11	Power Button	Long press for 3s to turn on/off the RC	Long press to turn the RC on/off. When the RC is on, a short press can be used to turn the screen on/off
12	R1 Button	Functional button in APP	Adapt to the function buttons on the lower right corner of the APP (for example, continue operation, end operation, previous step, next step, etc.)
13	R2 Button	Functional button in APP	Adapt to the function buttons on the lower right corner of the APP (for example, continue operation, end operation, previous step, next step, etc.)
14	RTK Point Marker	Mark the point with RC	High-precision RTK point marking
15	Status Indicator	Remote control status indication	Refer to the "Indicator Status" chapter
16	Battery Level Indicator	Remote control battery level	Indicate the power level of the remote control
17	HD Touchable Display Screen	For interface display and touch selection	Operate the drone and display the drone status
18	FPV Switch Button	Switch between the FPV camera and the full-screen map	
19	Centering wheel	Toggle the corresponding signal output of regulation	Supported only for industry applications
20	Air Outlet	Remote control air outlet	Do not cover the air outlet of the RC when using
21	Sealing Cover	Protect RC interface	
22	Type-C Interface	Remote control charging and upgrading interface	Please use the specified charger
23	USB Interface	For external USB devices	
24	Heat dissipation Outlet	Remote control heat dissipation outlet	Do not cover it when using
25	Spray Button	Turn on/off the pump	Turn on/off the pump in the manual mode
26	RC Handle	Convenient for users to hold and carry	
27	Customizable Button	Record the Point B in AB Point Mode by default;	Customizable

		Change to the right line by default in the Manual+ Mode	
28	Customizable Button	Record the Point A in AB Point Mode by default; Change to the left line by default in the Manual+ Mode	Customizable
29	Wireless Network Card Slot	For installing an external wireless network card	
30	Wireless Network Card Cover	Protect the wireless network card	

1.1.2. Antenna Placement

The antenna of the RC adopts a foldable design, and the signal strength varies with the positions of the antenna. It is recommended to keep the antenna vertical to the ground when you control the drone. In this case, the signal is the strongest. The position or distance between the RC and the drone is adjusted in time to ensure that the drone is always in the optimal communication range. Therefore, the antenna of the RC should not point to the drone during the flight. The recommended operation is shown in Figure 1-4.

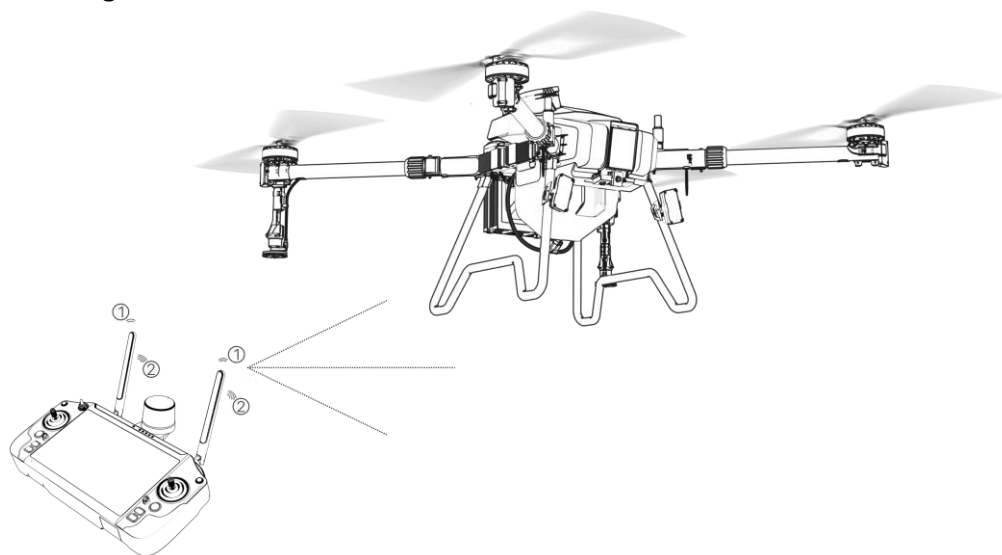


Figure 1-4 Signal Strength of the RC
1. Weak signal 2. Strong signal

Notes:

Do not fold the antenna during the flight to avoid obstruction between the RC and the drone, otherwise, the signal quality will be seriously reduced.

1.1.3. Indicator Status

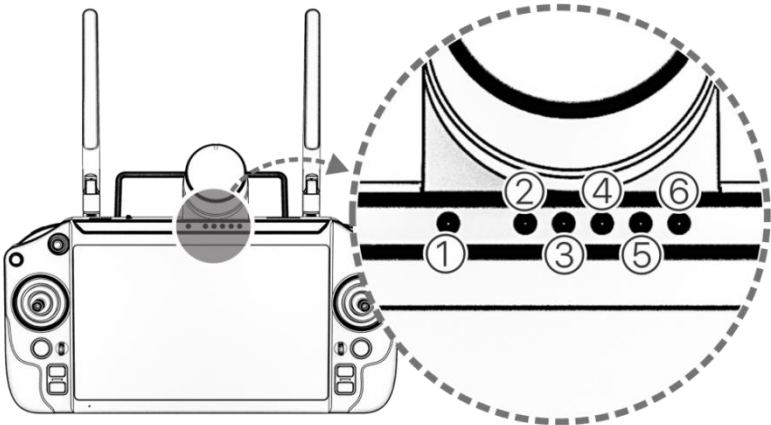


Figure 1-5 Indicator Status

The RC status indicator shows the status of the RC. The indicator will give priority to link status and warning messages.

Details are shown in the table below:

Indicator Status	RC Status	On/Off Status
Solid Red	RC is not connected to the drone	ON
Solid Green	RC is connected to the drone properly	ON
Cyan Flash	RC is pairing	ON
Green Flash	RC temperature is too high	ON
Red Flash	RC battery is low	ON
Blue Flash	The control stick is not in the middle position	ON
Solid Red	Charging and the battery level is less than 10%	OFF
Solid Yellow	Charging and the battery level is between 10% and 90%	OFF
Solid Green	Charging and the battery level is over 90%	OFF

1.1.4. Remote Control Charging

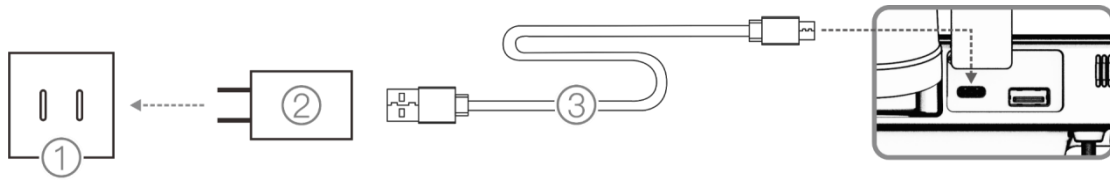


Figure 1-5

1. AC power supply 100-240V 2. USB charger 3. USB-C cable

Attention please:

1. Please use the Type-C interface to charge the RC.
2. Fully charged for about 4h with the designated quick charger.
3. Please use the official charger when charging the RC. If not, it is recommended to use an FCC/CE-compliant, 5V 2A charger or a 9V 3A fast charger that complies with the QC2.0 protocol.
4. To ensure the best condition of the RC battery, please make sure to fully charge the RC every 3 months.
5. If the RC is found to have a peculiar smell, smoke or liquid leakage, etc., stop charging and send it back for inspection and identification in time.
6. Do not charge the RC when the ambient temperature exceeds 60°C.
7. Keep the RC away from infants' and toddlers' reach while charging. It is recommended not to leave it unattended.

1.1.5. Frequency-Pairing Instruction

If the user purchases the drone as a whole set, the RC transmitter and the drone have been frequency-paired before dispatching and can be used directly after power-on. In other cases, use the following methods to match the frequency:

1. Turn on the RC parameter adjustment assistant, as shown below.

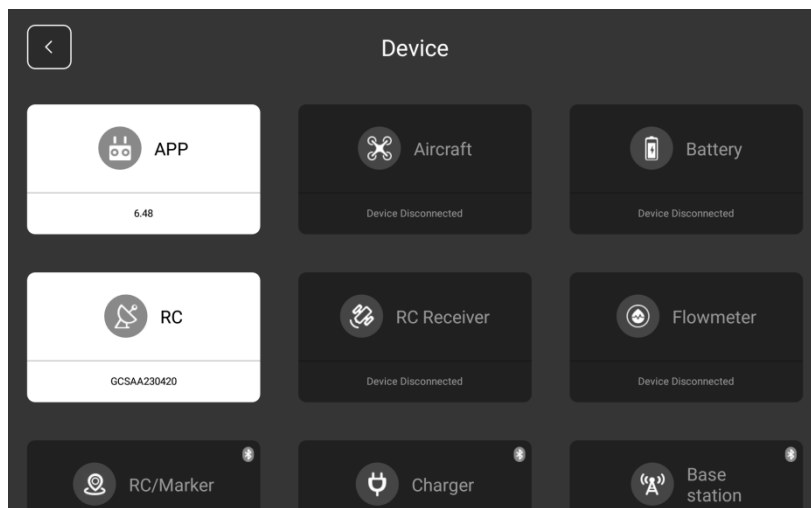


Figure 1-6

2. Click the “Start Linking” button, the indicator light of the RC will be flashing cyan. APP shows a pop-up of “frequency pairing” and there is a 30s time limit to turn on the RC.

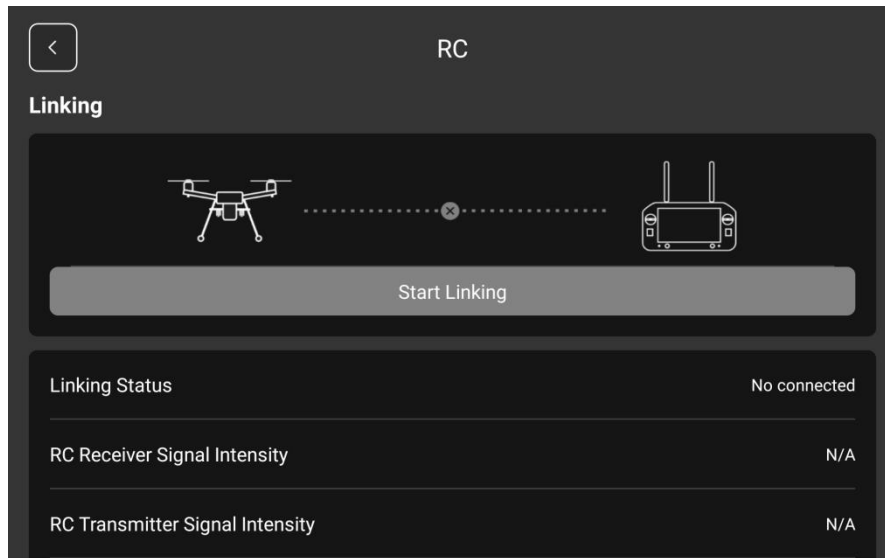


Figure 1-7

3. Long press the power button for 5 seconds until you hear a beep. “Pairing Succeed” will be shown on the APP interface. The RC indicator will be solid green. If you haven’t press the pairing button in 30 seconds, the pairing will be failed.

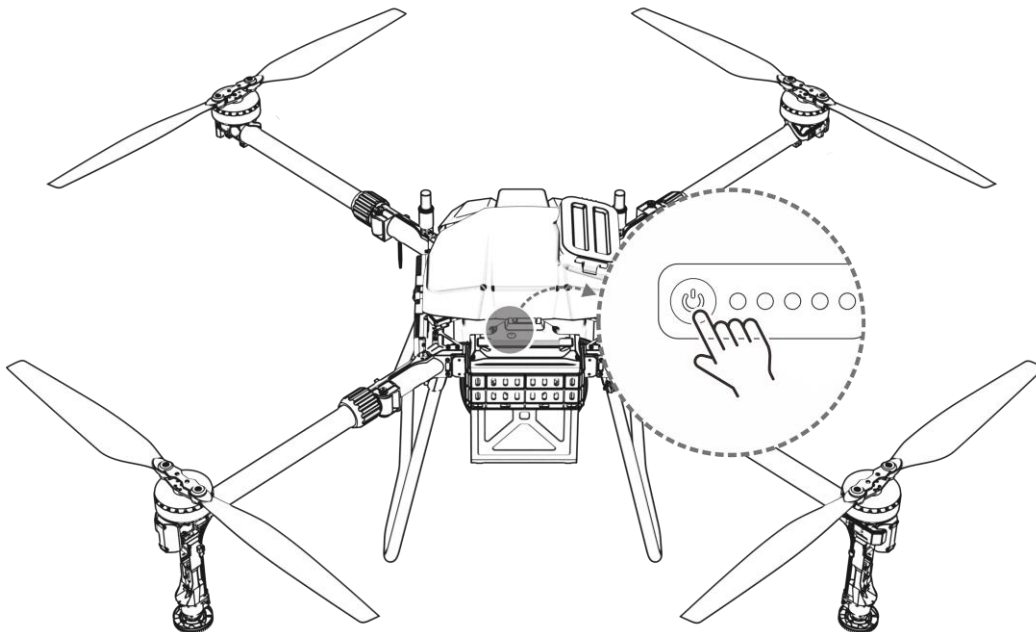


Figure 1-8

Notes:

1. Keep the distance between the RC and the receiver within 1m while pairing.
2. Ensure the propeller is removed from the drone during frequency pairing, and keep a safe distance from drone motors.

1.1.6. Specification Parameters

RC Datalink	
Frequency Range	2.400-2.483GHz
Signal Effective Distance (Outdoor, no obstruction, no interference)	Maximum communication distance 10km 3km image transmission (plant protection scenario)
Interference Recovery	<1s
Antenna Type	Omnidirectional antenna (2.5dBi)
Wi-Fi	
Protocol	IEEE 802.11a/n/ac, Wi-Fi compliant
Operating Frequency	4.900 GHz-5.845 GHz (5.0 GHz ISM Band)
Bluetooth	
Protocol Standard	Bluetooth 4.2
Working Frequency Range	2.400-2.4835GHz
Display	
Screen Size	7 inch
Touching Mode	Capacitive
Screen Resolution	1920x1200
Screen Brightness	1000cd/m ²
Other Parameters	
Operating System	Android OS
Operating Temperature	-15°C - 40°C
Storage Temperature	-25°C - 60°C
Charging Environment Temperature	5°C - 40°C
Battery Type	20000mAh @3.7V lithium battery
Charging Time	About 4h (using official fast charger)
Continuous Working Hours	More than 6h
Weight	About 1120g

1.2. Smart Battery Introduction

The battery equipped with this model is a polymer lithium power battery, featuring a

compact size, light weight and large capacity.

1.2.1. Component Definition

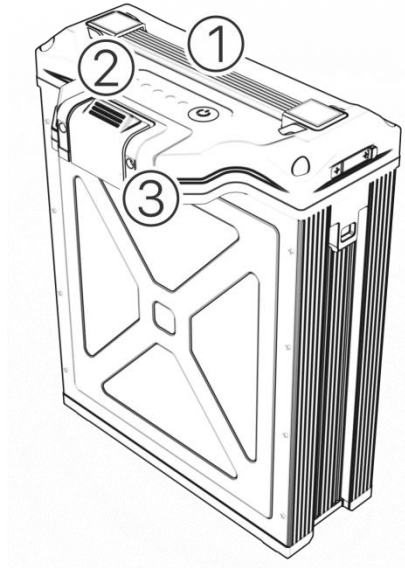


Figure 1-9 Battery Component
1. Handle 2. Indicator LED 3. Charging port

1.2.2. Specification Parameters

Subject	Parameter
Typical Capacity	20000mAh
Nominal Voltage	53.2V
Maximum Charging Current	100A (Environment Temperature $25^{\circ}\text{C} \pm 5^{\circ}\text{C}$)
Limited Charging Voltage	60.9V
Maximum Discharging Current	200A
Operating Temperature	$5^{\circ}\text{C} - 71^{\circ}\text{C}$ (Charge) $-15^{\circ}\text{C} - 75^{\circ}\text{C}$ (Discharge) Note: When the temperature of the battery cell is below 0°C , the discharge ability will be seriously restricted, which can not meet the requirements of normal use, and can be used normally after returning to normal temperature.
Storage Temperature	$-10^{\circ}\text{C} - 30^{\circ}\text{C}$ (It is recommended to perform power replenishment and maintenance once every 3 months)
Weight	About 8.2kg

1.2.3. LED Indicator Status

1.2.3.1. Battery Status Display

Function	Precondition	Operation	LED Indicator	Note
Battery Level Checking	Sleep/Power off	0 (Short Press)	Display the current battery level for 3s	The battery level will be displayed for 3s after a short press
Power On	Sleep/Power off	0-1 (Short Press+Long Press >1s)	0, display the current battery level; 0-1, turn off the display. The LED indicators will light up one by one, then display the current battery level	0-1 MOS has been activated after power on
Power Off	Power On	0-1 (Short Press+Long Press)	0, display the current battery level; 0-1, turn off the display. The LED indicators will go off one by one	0-1 MOS has been deactivated after power off
RC Pairing	Battery is activated and RC is on the pairing interface	In the power on status 2 (Long Press>5s)	The LED 3 and 4 will flash while pairing. After the pairing is completed, LED indicators will revert to the original status	
Disconnect UPS	Battery is activated	Short press for 5 times, 0-0-0-0-0	0, display the current battery level	UPS is deactivated

Notes: 0 means short press, 1 means long press, 2 means long press >5S.

1.2.3.2. Battery Level Display

Notes: "●" means always on; "⊙" means the light flashes; "○" means no light

LED5	LED1	LED2	LED3	LED4	Power Level
○	●	●	●	●	95%-100%
○	●	●	●	⊙	90%-94%
○	●	●	●	○	80%-89%
○	●	●	⊙	○	70%-79%
○	●	●	○	○	60%-69%

○	●	⊙	○	○	50%-59%
○	●	○	○	○	40%-49%
○	⊙	○	○	○	20%-39%
⊙	⊙	○	○	○	< 20%

1.2.3.3. Charging Status

LED1	LED2	LED3	LED4	SOC
⊙	⊙	○	○	0-59%
⊙	⊙	⊙	○	60%-79%
⊙	⊙	⊙	⊙	80%-100%

1.2.3.4. Error and Alarms

Situation	LED Indicator	Description	Notes
Upgrading	LED shows progress	Show upgrade progress	
High Charging Temperature Alarm	LED 5 flashes + LED 4 flashes 3 times/second	Battery charging temperature is too high	Stop charging
Low Charging Temperature Alarm	LED 5 flashes + LED 4 flashes 2 times/second	Battery charging temperature is too low	Stop charging
High Charging Voltage Alarm	LED 5 flashes + LED 3 flashes 3 times/second	Battery charging voltage is too high	Stop charging
Overcurrent Charging Alarm	LED 5 flashes + LED 2 flashes 2 times/second	Battery charging current is too large	Stop charging
Low Discharge Voltage Alarm	LED 5 flashes + LED 3 flashes 2 times/second	Battery discharge voltage is too low	Stop discharging
Short Circuit/Overcurrent Alarm	LED 5 flashes + LED 2 flashes 3 times/second	Battery discharge current is too large	Restores after one minute of unloading
Battery Failure Alarm	LED 5 is always on when powering on	The battery cell voltage is less than 1.5V or the voltage difference is greater than 1V	It is strictly prohibited to disassemble by yourself, please contact the after-sales

Notes:

1. Activate the battery only after it is well connected to the drone.
2. Disconnect the battery after it is turned off.
3. Charge the battery to 60% every 3 months to ensure a longer service lifetime.
4. Before using, ensure sufficient battery level. When the battery has not been used for a long time, please use the dedicated charger to discharge the battery to the storage voltage, and then store it in a dry and ventilated environment.
5. This battery needs to be charged with a dedicated charger (TC4501P). In order to avoid accidents, please do not change the charger in any condition.
6. Do not use batteries if they emit odors or heat, or they are in an abnormal shape/color or has any other problems. If the battery is in use or charging, it should be immediately removed from the drone or charger. Stop using this kind of battery.
7. It is normal that the flight time will be shortened when the ambient temperature is lower than 10°C.
8. The battery surface should be cleaned in time after the operation, in order to avoid agrochemical corrosion.
9. The drone is strictly forbidden to be used in the environment of strong static electricity, magnetic field or high voltage power line.
10. It is strictly prohibited to pierce the battery case with nails or other sharp objects, or to hammer or step on the battery.
11. If the electrolyte enters eyes after the battery leaks, rinse the electrolyte out instead of rubbing the eye. Seek medical help immediately. Eyes will be injured if not treated in time.

1.3. Charger (TC4501P)

TC4501P intelligent charger is a single-channel lithium-polymer battery charger with a built-in cooling system. It can achieve constant power charging with a maximum charging current of 83A.

1.3.1. Components

The definition of the charger components is shown in Figure 1-11 & 1-12.

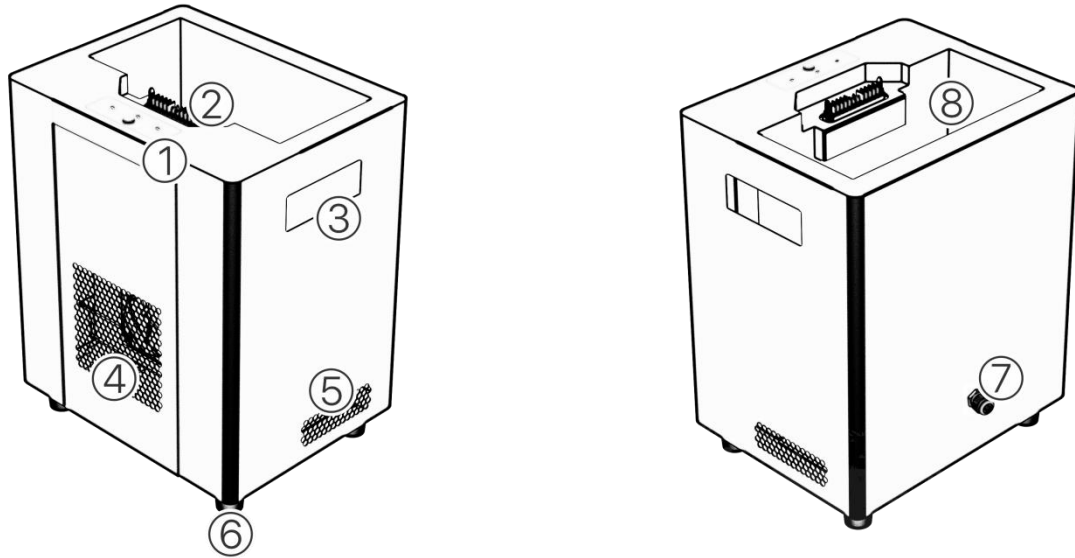


Figure 1-10 Charger Components

- | | | | |
|--------------------|----------------------|-------------------|-----------------------------|
| 1. Operation Panel | 2. Battery connector | 3. Handle | 4. Front Vent |
| 5. Side Vent | 6. Base | 7. AC Power Input | 8. Battery Supporting Frame |

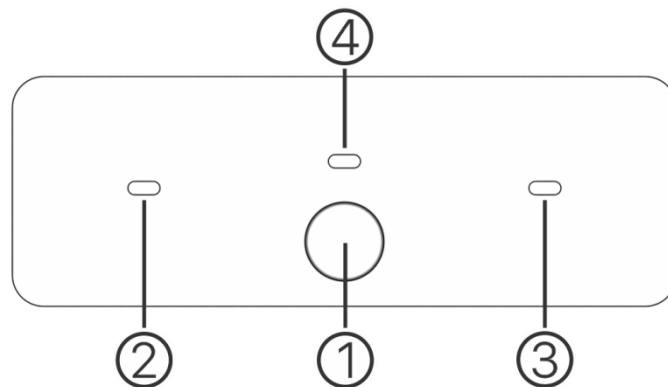


Figure 1-11 Charger Operation Panel

- | | | |
|------------------------|---------------------------------|----------------------|
| 1. Power on/off button | 2&3. Charging status indicators | 4. Warning indicator |
|------------------------|---------------------------------|----------------------|

1.3.2. Function Description

1.3.2.1. Button

1. Power On/Off: After the charger is powered on, short press to turn it on (indicator light will flash). Press briefly again to turn it off (indicator light will turn off);

2. Switch Between Slow/Fast Charging: After the charger is powered on, while in the on state, press and hold more than 2 seconds to switch from normal charging to fast charging (switching from 3200W to 4500W).

1.3.2.2. Indicator Lights

1. Power-on self-check:

Confirm that all terminals are correctly connected. When the charger power is turned on, both the charging status indicator and the alarm indicator light up. After a single beep, the lights go out, the self-test is completed, and the charging status indicator breathes normally. For the 220V system: 2 seconds on, 1 second off; for the 110V system: 1 second on, 1 second off.

2. Battery charging status indicator

LED Flashing Status	Prompt Sound	Description	Notes
OFF	/	No battery connected to the charging port	Battery not detected.
Yellow Solid On	/	Battery is connected to the charging port, waiting for charging	
Green Flashing	/	Battery is in charging state	
Green Solid On	/	Battery is fully charged	
Yellow Continuous Single Flash	/	Battery temperature is too low, so the charging current is limited	Check the battery current limiting flag.
Yellow Continuous Triple Flash	/	Battery temperature is too high, so the charging is prohibited	Check the battery over-temperature protection flag.
Red Single Flash	D.D.D...	The battery is not plugged in/unofficial battery/communication error	No communication with voltage or communication with no voltage.
Red Triple Flash	D.D.D...	BMS error(excluding battery low temperature protection and high temperature protection)	
Red Solid On	D.D.D...	Output over-voltage/other hardware error	Re-powering to recover
Blue Solid On	/	Incompatible battery type, charging is prohibited	

3. Charger warning indicator

LED Flashing Status	Prompt Sound	Description	Notes
Yellow Single Flash	/	Charger temperature is too high	Self-directed derating

Yellow Double Flash	/	Input voltage is under voltage	Self-directed derating
Yellow Triple Flash	/	Input voltage is high	Charge normally
Red Signal Flash	D.D.D...	Ambient temperature is too high or fan malfunction	Stop charging
Red Double Flash	D.D.D...	Abnormal charger input voltage (undervoltage protection, voltage is less than 155V)	Stop charging
Red Triple Flash	D.D.D...	Abnormal charger input voltage (Over-voltage protection, voltage is more than 285V)	Stop charging
Red Solid On	D.D.D...	Output over-voltage or other hardware faults	Stop charging, power off and restart to
Blue Solid On	/	Normal charging	3200W is suitable for mains power
Green Solid On	/	Fast charging	4500W is suitable for generators
Blue Single Flash	/	Harmonic alarm	Reduces power to 80% of the set power
Blue Double Flash	/	Harmonics too high	Stop charging

4. Activation indicator

Status	Prompt Sound	Battery Status Indicator	Warning Indicator	Indicator Light
Deactivated	/	Solid White	Solid White	FLASH
Activated	/	OFF	OFF	FLASH

1.3.2.3. Cooling System Working Logic

During the charging process, if the charger detects that the battery temperature or the charging board temperature is too high, the cooling fan will be activated. The fan speed is intelligently adjusted based on the temperature.

1.3.2.4. Charging Steps

Step 1: Insert the power cable to the charger's power port, and insert the other connector to the AC power supply (100-240V, 50/60Hz).

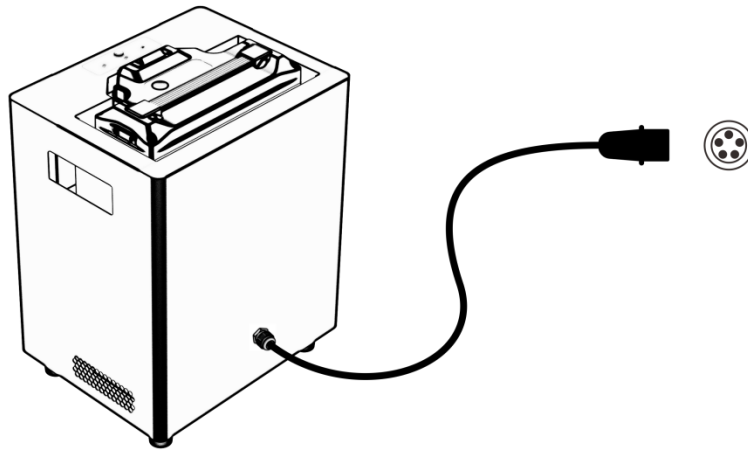


Figure 1-12 Charger Power Cable Connect

Step 2: Put the battery into the charger. Please pay attention to the direction of the connector. Check that there are no foreign objects at the bottom of the charger. After placing it, check whether the battery is in place.

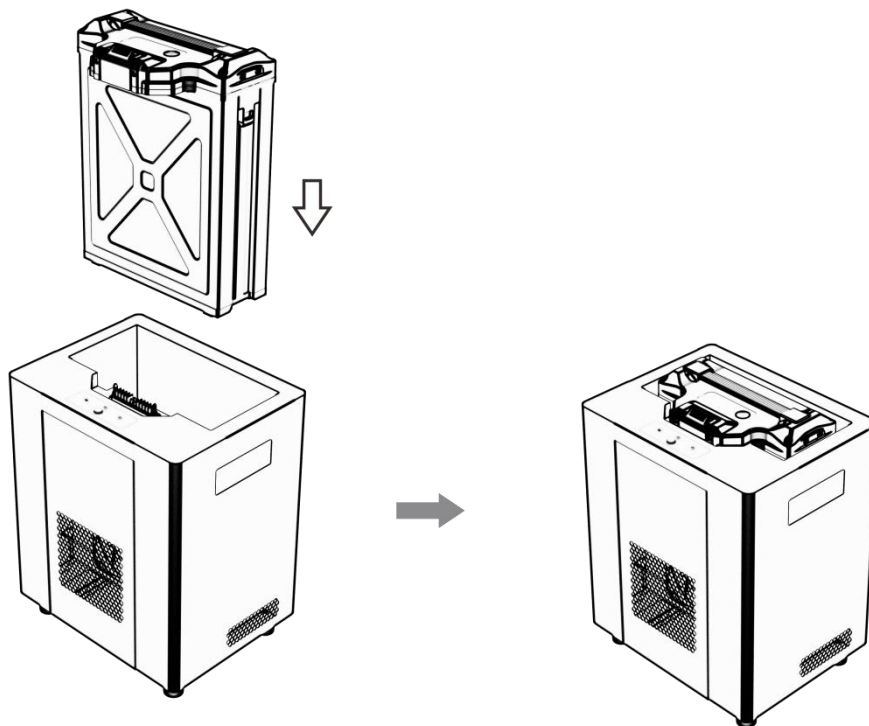


Figure 1-13 Battery Placement

Step 3: After making sure that all wires are connected correctly, press the “Start/Stop” button in the operation panel, and the charger will start self-check. If some error occurs during the self-test process, please refer to the indicator status chapter.

Step 4: Press the "Start/Stop" button in the operation panel to turn off the battery after charging, unplug the AC power cable, and unplug the battery. Please follow the rules below:

Charging Mode	Battery State	Channel Indicator State	Plug or Unplug Battery Instruction
Fast Charging / Normal Charging	Fully charged	Solid Green	Unplug battery directly
	Charging	Green Flashing	If plugging or unplugging is needed, please press the start/stop button first. Plugging or unplugging directly is prohibited

Notes:

1. Do not use the product in direct sunlight, high humidity, high temperature, dust, vibration or thunder/lightening.
2. Products should be kept away from dangerous substances such as high pressure, heat source, corrosive agent, flammable gas, etc., and must be used at appropriate ambient temperature (5-45°C is recommended).
3. The product should be placed horizontally and stably, ensuring good ventilation and heat dissipation conditions during operation.
4. When charging, please strictly follow the battery safety instructions and cautions.
5. Before connection, please ensure that all ports and input lines of modules and batteries have no obvious defects such as blockage, damage, breakage or short circuit.
6. Before use, please ensure that the power supply line has enough capacity to avoid overheating or even fire caused by insufficient capacity, especially when two or more pieces of equipment are used at the same time.
7. Do not pull out the input wire or battery when the charger is working. Pull out the battery in time after charging.
8. Be sure to place the battery in place before starting charging.
9. The cooling box has a limited load-bearing capacity. Do not load the battery for transportation, otherwise the battery and charger may be damaged.
10. This charger is only applicable to the battery of this drone. If the user uses the charger for purposes other than those listed in the manual, the Company shall not assume any responsibility.
11. Do not leave the charger unattended when it's working. If any function is not normal, please stop charging immediately.

12. In case of fire, do not use liquid extinguisher to avoid electric shock. Use dry powder extinguisher correctly.

1.3.3. Specification Parameters

Subject	Parameter
Input Voltage	AC 100-240V/50-60Hz
Output Power	4500W(Max)
Output Voltage	DC 60.9V(Max)
Output Current	83A(Max)
Charging Mode	Constant power charging
Working Temperature	-5°C - 45°C
Working Humidity	0% - 75%
Storage Temperature	-10°C - 70°C
Storage Humidity	0% - 75%
Voltage Detection	Support
Protection	Over-current protection Over-temperature protection Over-voltage protection Short circuit protection

1.4. Spreading System (Optional)

1.4.1. Introduction

The spreading device is an essential component of agricultural drones. Compared to traditional manual spreading methods, which are inefficient, costly, and have poor uniformity, the drone spreader significantly enhances spreading efficiency, reduces costs, and improves spreading quality.

Centrifugal Spreading: The spreader uses the high-speed rotating material disc to uniformly throw particles, it features a wide spreading range and easy adjustment.

Precision Spreading: Equipped with the built-in rolling feeder, allowing precise control of the material discharge volume by adjusting the discharge rate in real-time based on the preset dosage and flight speed.

Application Scenario: Seeding of rice, wheat; fertilizer spreading; fish food feeding, etc.

1.4.2. Spreading System Installation

1.4.2.1. Preparation

Since the spraying system and the spreading system share the 3WWDZ-U30B platform, the components of the spraying system need to be removed before the spreading system is installed. The replacement process takes less than 10 minutes.

Notes: During the replacement, the batteries must be removed from the drone!

1.4.2.2. Spraying System Removal

1. Remove the two plugs of the spray/spread on the HUB module and pull the wire out of the cabling holder on the tank.

Notes: Prevent agrochemical (neither liquid nor solid) from the port during the removal.

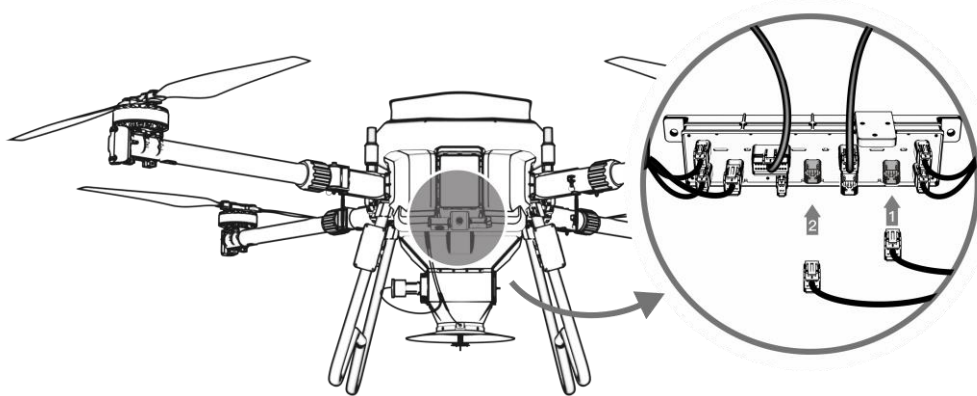
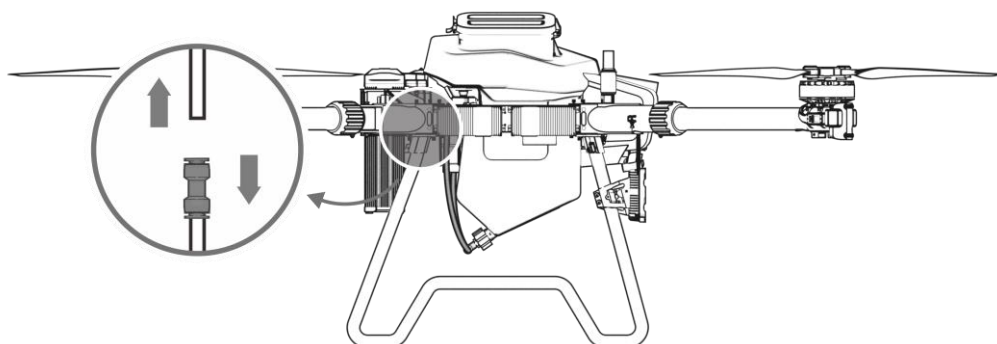


Figure 1-14

2. Unplug the quick disconnect connector of the pipe on both sides of the drone to remove the pipe between the pump and the nozzle.

Notes: If you need to switch the spraying system to spreading system, it is recommended to apply some liquid on the head of the pipe for lubrication.



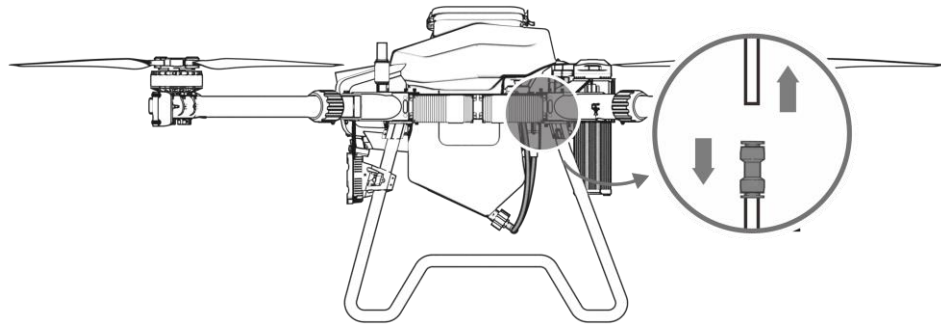


Figure 1-15

3. Remove the tank up straight from the drone.

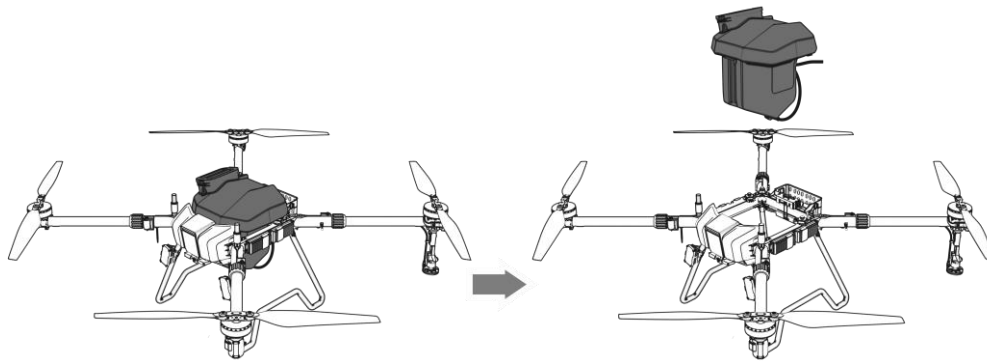


Figure 1-16

Notes: Do not scratch the surrounding wire during the tank removal.

1.4.2.3. Spreading System Installation

1. Tilt the spreader into the body frame as shown in the figure. Do not scratch the surrounding wiring. Adjust the tank to make sure its supported by four weight sensors. Prevent agrochemical (neither liquid nor solid) from the port during the installation.

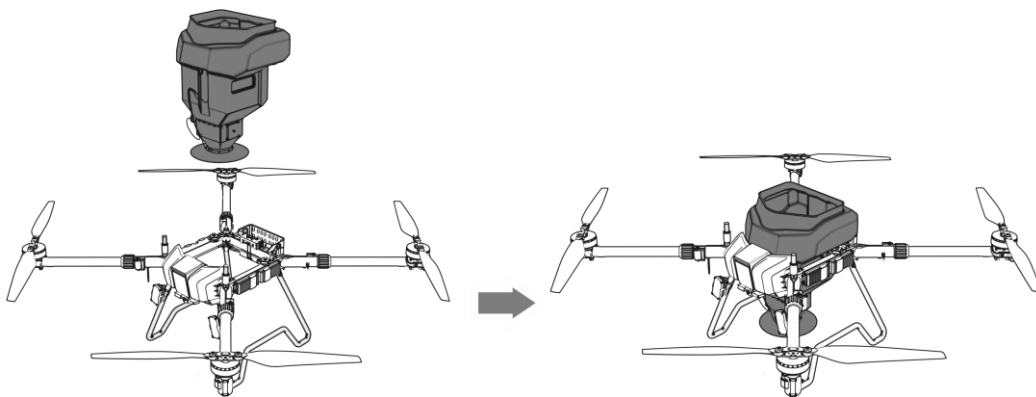


Figure 1-17

2. Insert the two plugs of the spray/spread outgoing line into the two reserved

interfaces on the HUB module of the spreader respectively. Fix the wire on the clamp on the container.

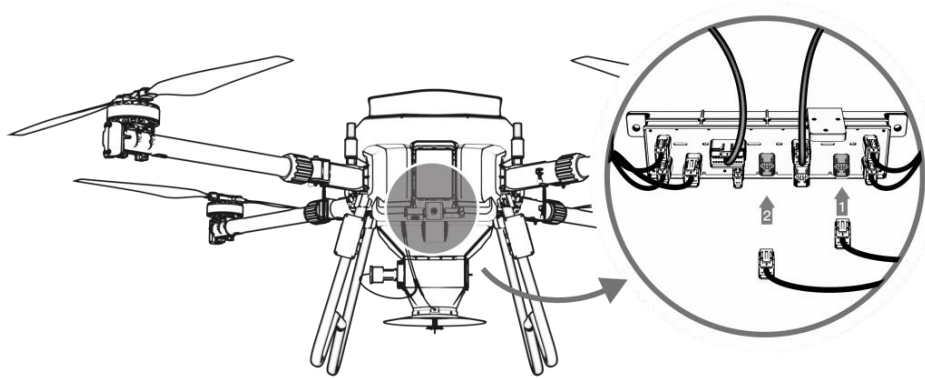


Figure 1-18

1.4.3. Spreader Basic Operation

1.4.3.1. Usage

1. Turn on the remote control and the drone according to the instruction.
2. Enter the Agriculture Assistant APP after step 1 finished.
3. For the first time use of spreading system, please enter the setting interface. Choose the corresponding spreader type in the operation mode list.
4. Choose the roller type and material type in the setting interface according to the actual situation.

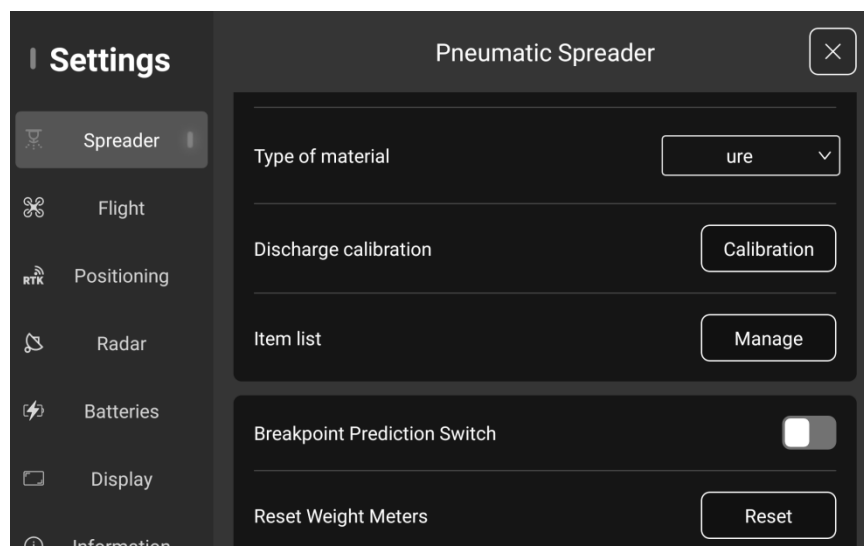


Figure 1-19

5. Set the dosage, route spacing and operating height in the parameter setting interface. The parameter will be different in different scenario. Please adjust the parameters and conduct tests based on the materials and scenarios used to

achieve the best operational results.



Figure 1-20

Notes:

1. Please keep the granule for operation dry.
2. If you change the granule or rolling feeder, please operate the calibration.

1.4.3.2. Spreading System Calibration

Preparation:

1. Please prepare the granule before the calibration. Place the drone on the plain surface, and completely empty the container.
2. Select the type of rolling feeder and granule type. If the granule is used for the first time, click "Manage" to name it.

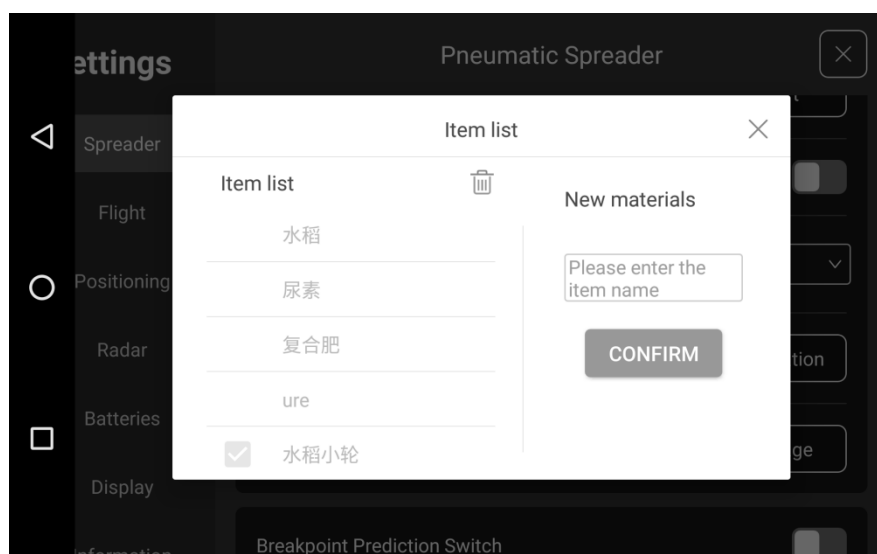


Figure 1-21

3. Click the Calibration to enter the calibration interface. Please operate according to the guidance on the APP. Here are the steps:

Step 1: Place the drone on a plain surface and make sure the container is empty.

Notes: If the drone is not placed on a plain surface and the offset angle is large, the next steps of calibration cannot be operate.

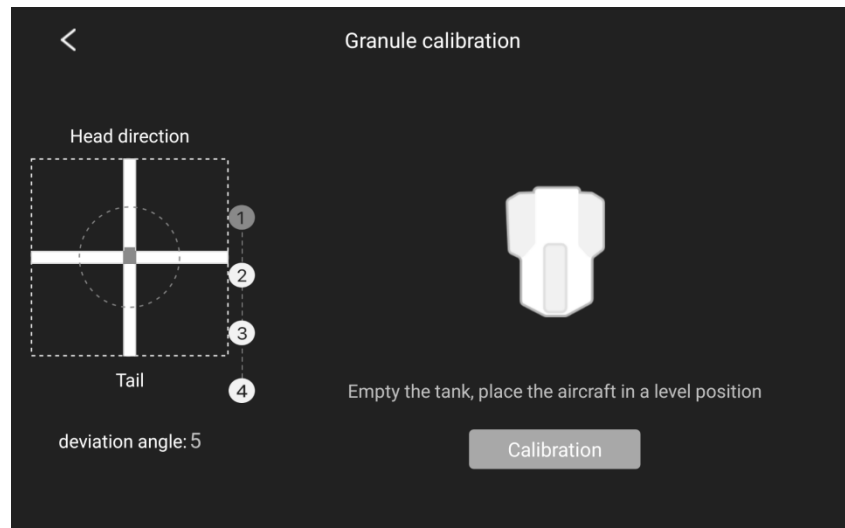


Figure 1-22

Step 2: Click 'Tare'

Notes: If the tare calibration has been completed before, click "Skip".

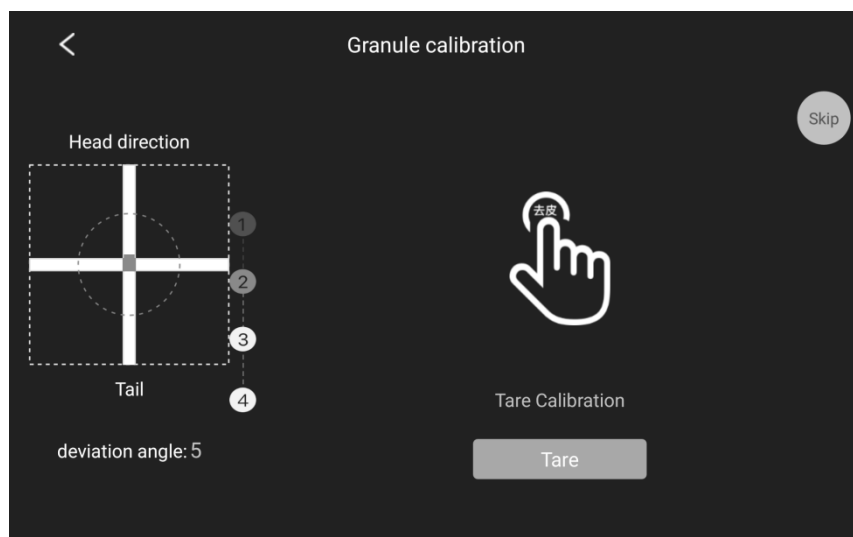


Figure 1-23

Step 3: Fill the container. Click "Complete" after filling it, the calibration will start automatically.

Notes: Do not touch the drone during the calibration.

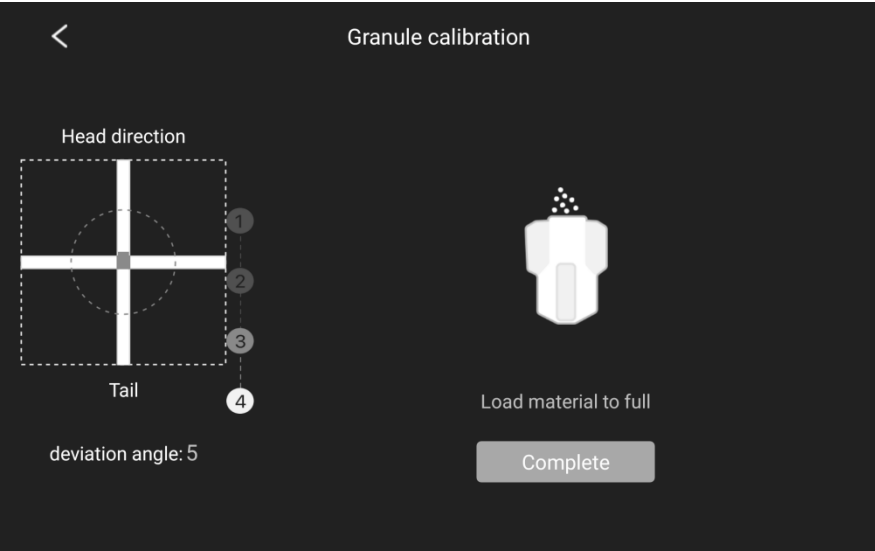


Figure 1-24

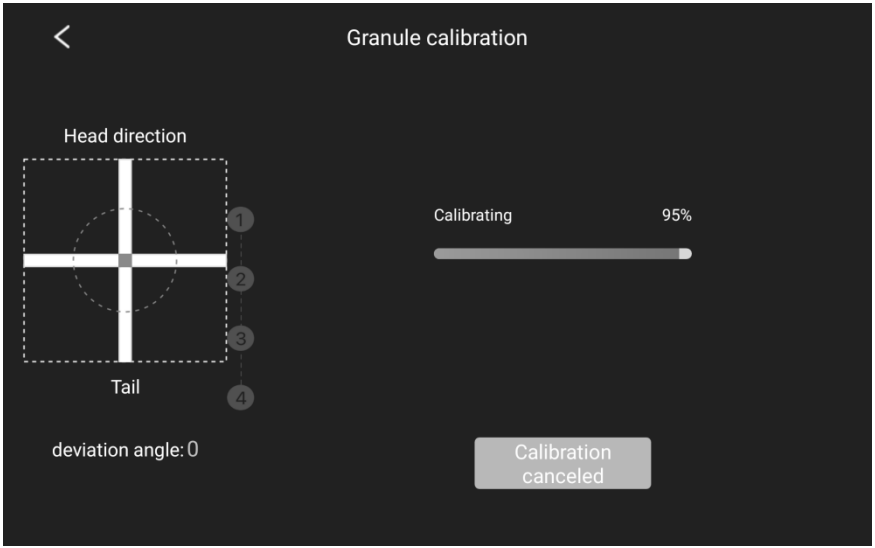


Figure 1-25

Step 4: The calibration coefficient will pop up when the calibration is completed.

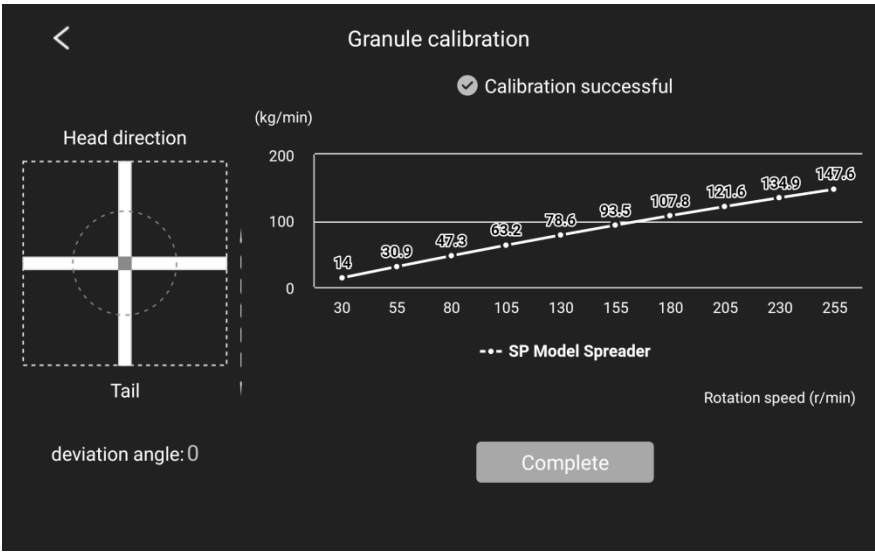


Figure 1-26

Notes: If the calibration fails, please repeat the calibration according to the above steps.

1.4.3.3. Spreading Test

There is a spreading test function in the setting interface. Users can click the Start button before operation to make sure the rolling feeder and the centrifugal disk work properly.

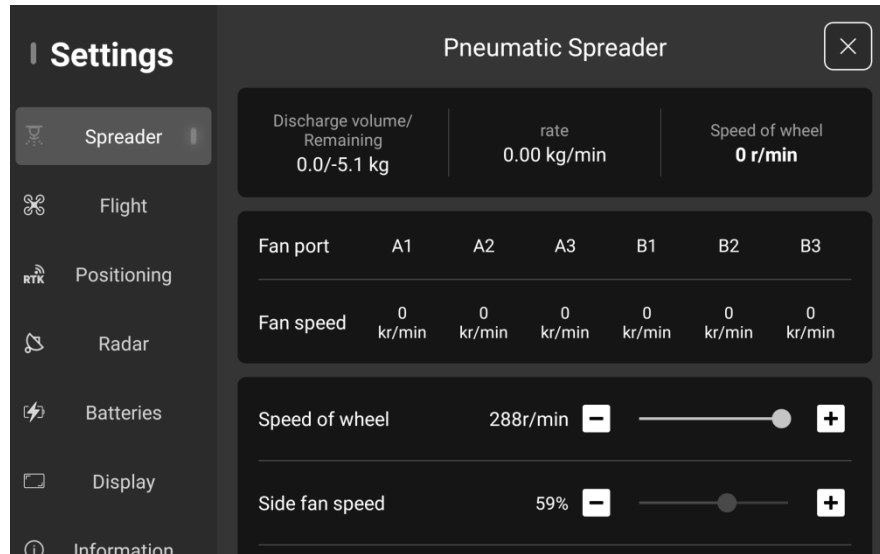


Figure 1-27

1.4.4. Specifications

Specification	
Dimensions	456*423*638mm
Weight	4.8kg(including tank and spreader)
Volume	45L
Electrical Parameters	
Rated Voltage	53.2V
Rated Power	600W
Protection Level	IP67
Performance	
Particle Size	1-10mm (Solid particles)
Broadcast Width	5-7m (Depends on the operation height, seed weight,

	shape, wind speed, and dosage)
--	--------------------------------

1.5. Drone Introduction

1.5.1. Functional Features

3WWDZ-U30B agricultural drone has the following features:

1. Made of professional carbon fibers with lighter weight and higher strength. Foldable arms are designed for easy transportation.
2. The pluggable tank and battery make mode changing easier, enhancing operational efficiency.
3. With a high-precision GNSS navigation system and IMU sensor, the drone has an accurate positioning function to ensure safety and reliability.
4. With large flow metering-pump, it provides excellent atomization and strong penetration.
5. The Agriculture Assistant APP supports smart route planning so that the drone can operate autonomously. It helps to make the pilot's work easier.
6. Environmentally friendly with no exhaust emissions, aligning with energy-saving, eco-friendly agricultural development. It's easy to maintain, with low usage and maintenance costs.

1.5.2. Drone Components

Drone components are shown in the figure below.

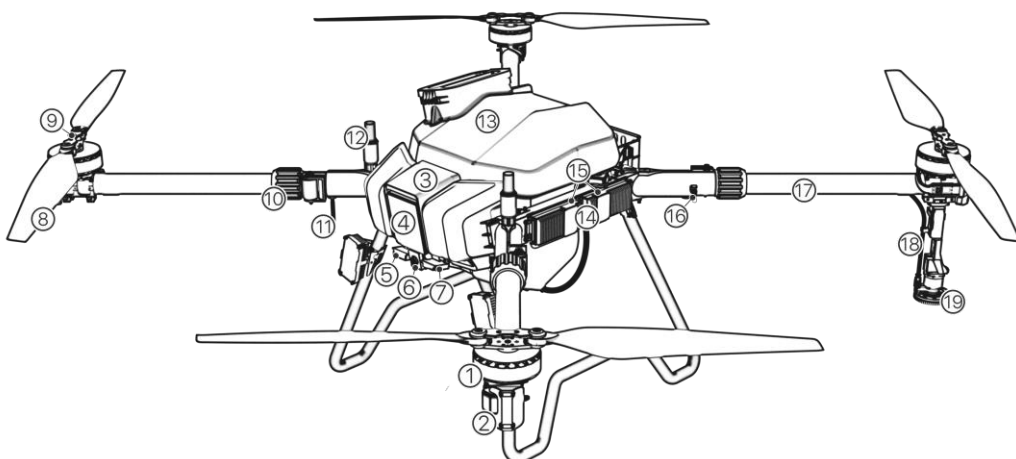


Figure 1-28

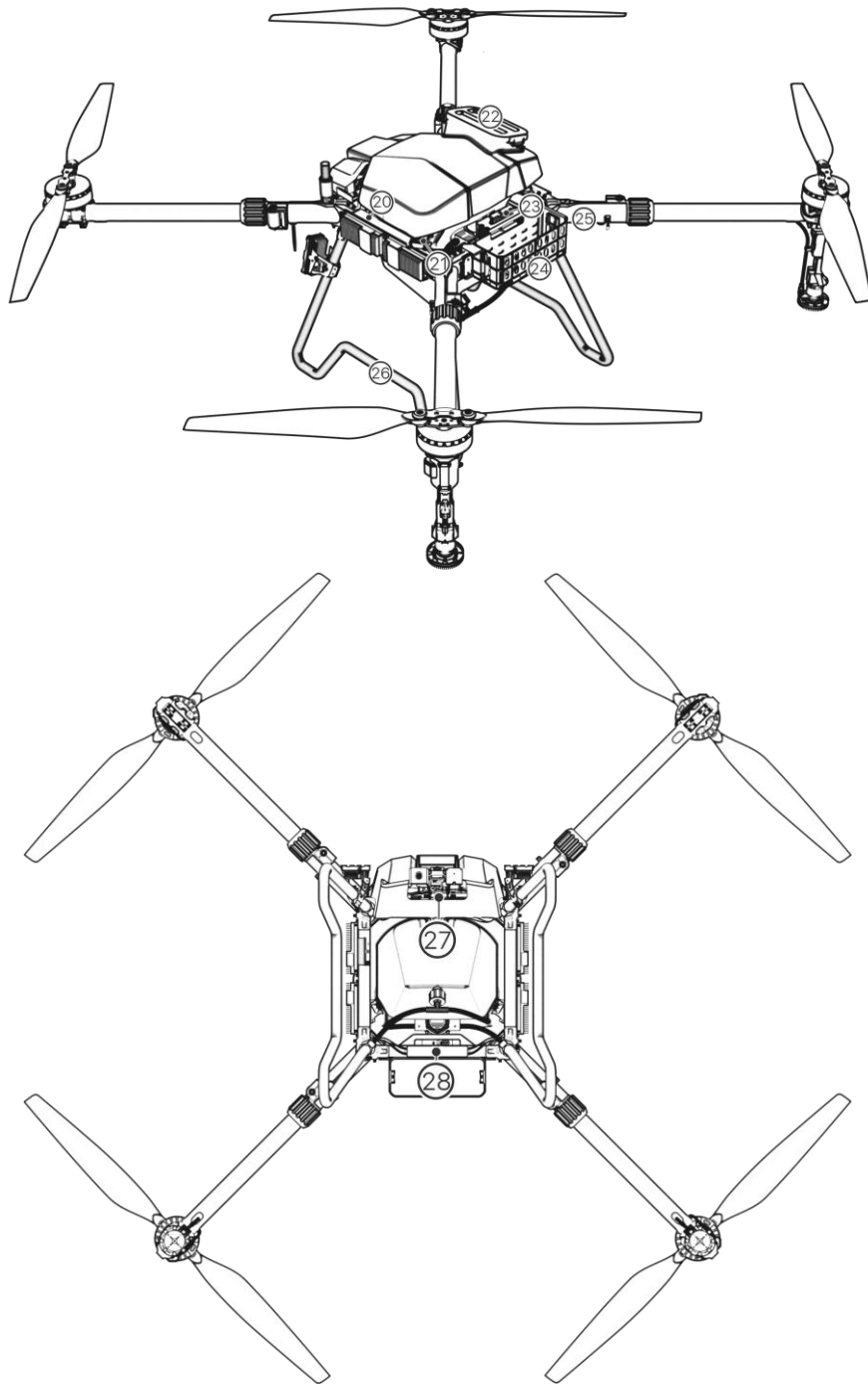


Figure 1-29

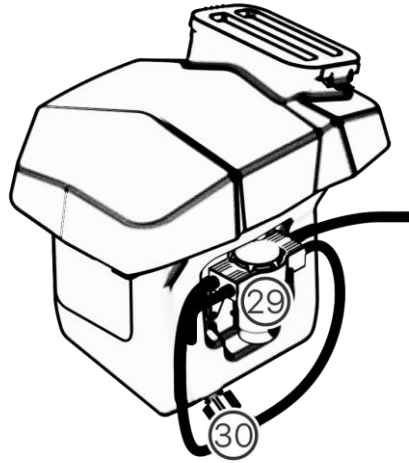


Figure 1-30

1. Motor	2. Motor Cover	3. Front Housing	4. Front FPV Camera	5. Front Obstacle Avoidance Radar	6. Mechanical PTZ
7. Terrain Following Radar	8. Propeller	9. Propeller Clips	10. Folding Arm Sleeve	11. Antenna	12. RTK Antenna
13. Spraying Tank	14. Electronic Speed Controller	15. Status Indicator	16. Folding Bayonet	17. Arm	18. Wind-Pressure Centrifugal Nozzle
19. Spraying System Distribution Board	20. Name plate	21. Weight Sensor	22. Tank Inlet	23. Battery Connector	24. Battery Basket
25. Folded Arm	26. Landing Gear	27. Hub Board	28. Current Manifold	29. Metering-pump	30. Tank Outlet

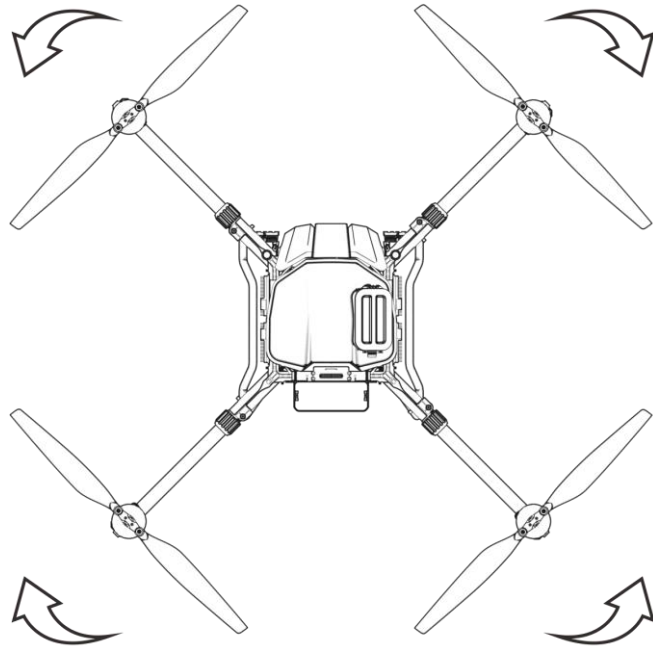


Figure 1-31

Notes:

The propellers on **arm 1** and **arm 3** rotate counterclockwise, while on **arm 2** and **arm 4** rotate clockwise. See Figure 1-32.

1.5.3. Drone Preparation

1.5.3.1. Unfold Arms

Step 1: Take 3WWDZ-U30B drone out of the box.

Step 2: Horizontally rotate the propellers to remove them from the holder.

Step 3: Unfold the arms. See Figure 1-33.

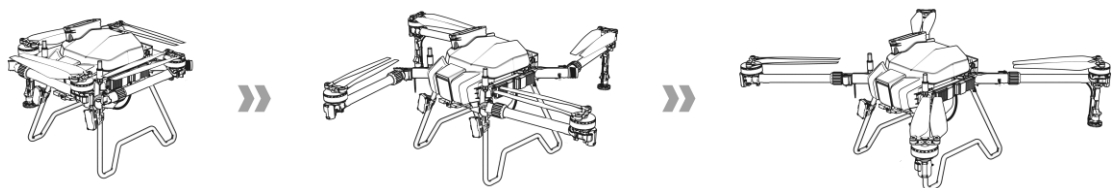


Figure 1-32 Arm Unfolding

Step 4: Make sure the clamping component is tightened, as shown in Figure 1-34.

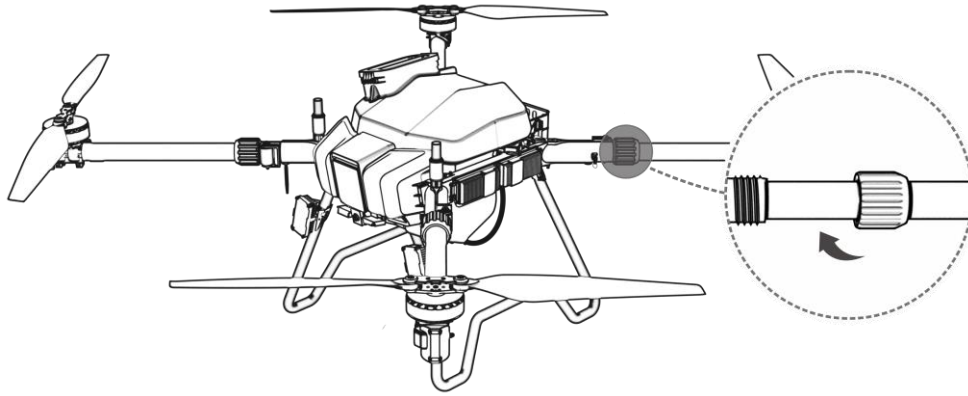


Figure 1-33 Arm Clamp

Step 5: Unfold the propellers to 180°, as shown in Figure 1-35.

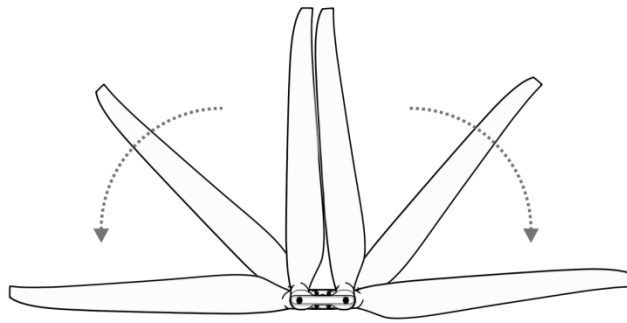


Figure 1-34 Unfold the Propellers

Notes: Be careful with your hands during the above process.

1.5.4. Install Drone Battery

Be sure to use the official battery and check the battery level before flying.

Step 1: Put the smart battery in the battery rail on the rear of the drone and make sure the battery is placed vertically downward into the rail.

Step 2: Connect the battery output port to the body, and the battery is locked in when you hear a “click”. See Figure 1-36.

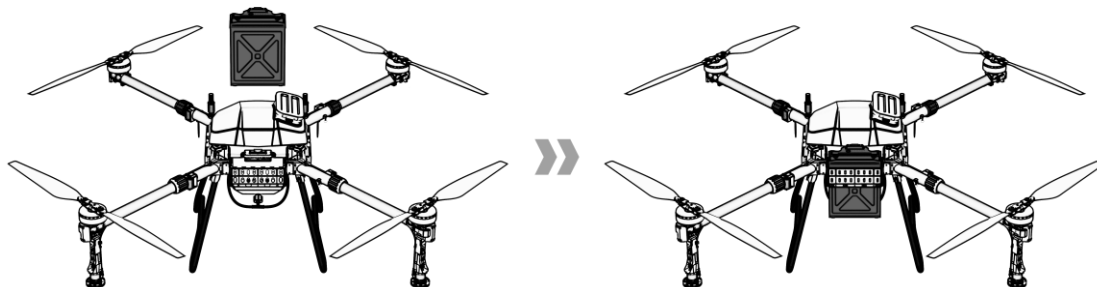


Figure 1-35 Insert the battery

1.5.5. Drone Calibration

1.5.5.1. Compass Calibration

Method 1: Access the calibration function via remote control

Step 1: Pull down the throttle.

Step 2: Quickly toggle down "Flight Mode Switch" to the down position ("S") and toggle it up to the up position ("G") for about 6-10 cycles until the status indicator light flashes blue.

Step 3: Place the drone head forward and keep the drone level with the ground. Slowly rotate the drone clockwise for at least one circle. If the status indicator flashes green, process to **Step 4**. If the status indicator is solid green, the calibration is completed.

Step 4: Lift the drone horizontally for more than 45° to the ground. Slowly rotate the drone clockwise for at least one circle until the status indicator shows solid green for 4s. The calibration is completed.

Step 5: Calibration fails if the status indicator shows solid red for 4s. Repeat **Step 2-4** until the operation succeeds. See Figure 1-37.

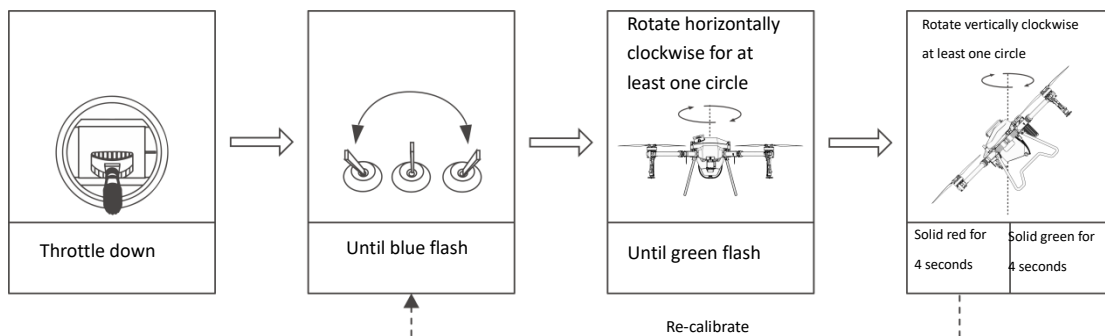





Figure 1-36 Compass Calibration

Method 2: Enter the calibration function via APP

Step 1: Click  on the right top in the APP to enter the Setting interface, and click  into Flight Setting.

Step 2: Click  to enter the magnetic compass calibration interface. Click to start the calibration, and the drone navigation light flashes blue.

Step 3: Repeat the **Step 3-5** in **Method 1**.

Notes:


1. Before calibration, the propellers on the drone should be removed.
2. Do not calibrate it in areas with strong magnetic fields, such as magnetic mines, parking lots, building areas with underground steel reinforcement, etc.
3. During the calibration, do not carry ferromagnetic materials, such as keys, mobile

phones, etc.

4. Do not calibrate the compass indoors.

1.5.5.2. Flowmeter Calibration

When using the drone for spraying operations for the first time, be sure to perform flowmeter calibration to avoid affecting the operation effect.

Preparation before calibration: Press “” button to start the pump when the drone is on the ground to discharge the air from the pipeline.

Enter “Setting”, “Spraying” interface. Click “Flowmeter Calibration”.

Notes:

1. Re-calibrate after replacing with different nozzles.
2. Re-calibrate after replacing agrochemical with different viscosity.
3. Re-calibrate if the error between the actual operation area and theoretical operation area is more than 10%.

2. Flight

2.1. Flight Instructions

According to the regulations of the International Civil Aviation Organization (ICAO) and national air traffic control on airspace control and the regulation of drones, drones must fly in the prescribed airspace. For flight safety, the flight restriction function (including altitude and distance restrictions and no-fly area) is enabled by default to help users to use the product safely and legally.

When GNSS is available, the no-fly area affects the flight together with altitude and distance restriction. The drone flyable airspace is the intersection of restricted airspace. Without GNSS, the drone flight height is not limited by Agriculture Assistant APP.

2.1.1. Altitude and Distance Restriction

Height limit is used to limit the flight height of the drone, and maximum radius is used to limit the flight distance. As shown in Figure 2-1, point "P" is the drone position at startup. "H₂" is the maximum flight altitude, which is set to 30 meters by default from the factory; "R" is the maximum flight radius, which is set to 2000 meters by default from the factory.

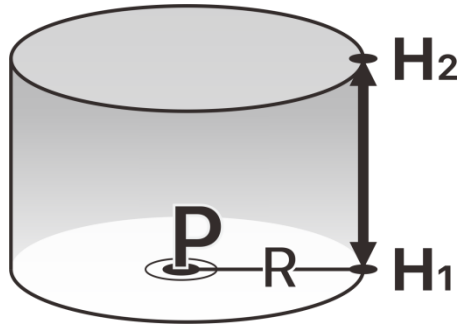


Figure 2-1 Altitude and Distance Restriction

GNSS State	Flight Mode	Flight Limit		Notification
With GNSS	GPS mode and autonomous mode	Max altitude	30m	Warning
		Max radius	2000m	Warning
	Gesture mode	Max altitude	30m	Automatically switch to GPS mode with warning
		Max radius	2000m	Automatically switch to GPS mode with warning
Without GNSS	Gesture mode	Max altitude	30m	No warning
		Max radius	No limit	No warning

Notes:

1. When the drone exceeds the boundary limit due to inertia, the remote control will still have control, but it cannot direct the drone to continue beyond the boundary.
2. To ensure flight safety, avoid flying near airports, highways, stations, and other densely populated areas.
3. If there is no GNSS signal during the flight, the drone will automatically switch to gesture mode and the app will display a safety alert. In this case, be sure to fly cautiously to avoid exceeding the maximum flight radius set by regulations.

2.1.2. No-Fly Zone and Restricted Area

2.1.2.1. No-Fly Zone

The area includes airport restricted flight areas and special flight restricted areas. For more details, please refer to special flight restricted areas defined by local authorities.

2.1.2.2. Restricted Area (when GNSS is available)

Areas are temporary restricted for flying due to emergencies (such as forest fires, large-scale events, etc.). The restricted area can be a circle or a polygon. The drone is not allowed to fly within the no-fly zone. See Figure 2-2.

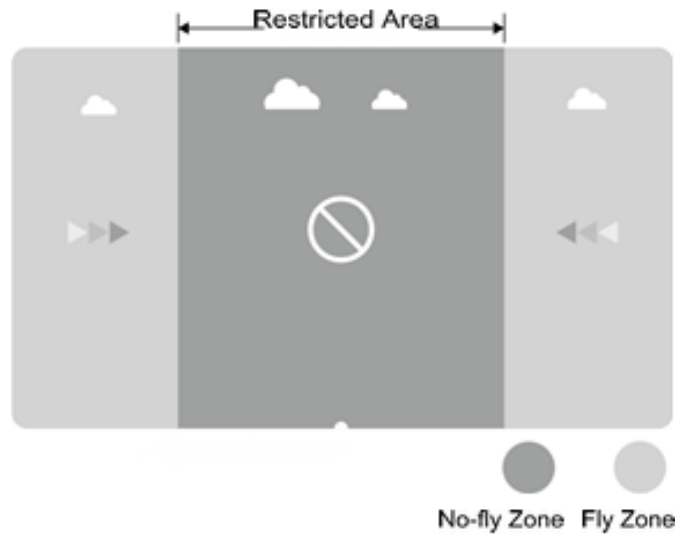


Figure 2-2 No-fly zone and restricted area

When GNSS Signal Is Normal		
Area	Special Area with Flight Restriction	Status Indicator Light for the Drone
No-fly Zone	The motors can not be activated.	Red light solid on for 5s and off in 1s
	If the drone flies without GNSS, it will land automatically immediately after GNSS is available, and the motor stops automatically after landing.	
Close to No-fly Zone	Distance to the no-fly zone <120m. The drone flight speed will slow down with flashing lights and alarming.	Red light solid on for 5s and off in 1s
Fly Zone	The drone can fly normally. No flight restrictions.	No warning

Notes: For flight safety, please avoid airports, highways, railway stations, subway stations or urban areas. If users need to fly in such areas, prepare relevant materials and apply for temporary airspace to local authorities. Then contact the after-sales service to release the restriction.

2.2. Indicator Description

On the first test flight, it is recommended to understand the meaning of the flight status indicators to ensure a safe flight.

No.	Status	Content	Indicator Display
-----	--------	---------	-------------------

1	Normal	Power on Self-check is completed GPS satellite searching	Flash yellow for twice
2		Preparation is completed; waiting for take-off	Solid yellow
3		Taking-off and flying	Head direction, solid red; Opposite head direction, solid green
4		Mode switch	Flash green for 5s
5		Magnetic compass calibration (Horizontal)	The indicator flashes yellow twice per second
6		Magnetic compass calibration (Vertical)	The indicator flashes green twice per second
7		Magnetic compass calibration succeeds	Solid green for 4s
8	Abnormal	Magnetic compass calibration failure	Solid red for 4s
9		Self-check Failed	Solid red
10		Low Voltage/Volume Level I	Flash red slowly
11		Low Voltage/Volume Level II	Solid red
12		IMU failure	Solid red
13		Barometer failure	Solid red
14		GPS failure	Solid red
15		Motor failure	Solid red
16		RC lose control	Solid red

2.3. Operation Description

2.3.1. Pre-flight Inspection

Please check the following points to avoid flight accidents.

1. Place the drone in the open operation area and the user should face the tail.
2. Make sure that the battery of the drone is installed properly.
3. Before flying, it is necessary to turn on the remote controller before plugging in the battery of the drone.

4. Ensure the battery of the drone and the remote controller are adequately charged, also the agrochemical required for spraying is sufficient.
5. Make sure that the motors and propellers rotate in the correct direction and the structure is stable. All arms and propellers of the drone have been fully extended, and the arm sleeves have been tightened.
6. Make sure that the spraying pipes are free of blockage and leakage, and the nozzles can spray water normally.

2.3.2. Lock and Unlock

2.3.2.1. Unlock

The unlocking operation is shown in Figure 2-3. When you unlock the drone, the motors rotate in the sequence of No. 1, No. 2, No. 3 and No. 4. When motor No. 1 starts, push the throttle slightly up and all the motors will start at the same time.

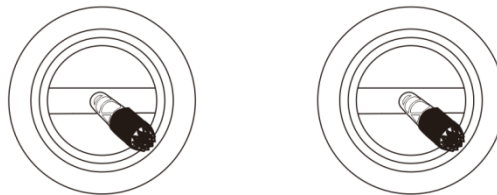


Figure 2-3 Unlock

2.3.2.2. Lock

The drone supports two active locking methods:

1. Perform the operation shown in Figure 2-4 to lock the drone.
2. After the drone lands, the throttle stick should be kept at the down position for at least 3s, and then the drone will be locked automatically.

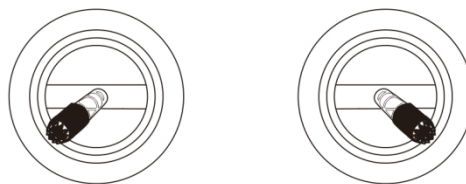




Figure 2-4 Lock

2.3.3. Take Off & Land

2.3.3.1. Take Off

Step 1: Click on “” and then long press “” for 2s to turn on the remote controller.

Step 2: Turn on the power supply of the drone.

Step 3: The pilot should keep a distance from the drone of more than 10m. Enter the operation interface of the Agriculture Assistant APP to ensure that the signal of GNSS is good, and the status indicator light of the drone is not showing red, which means there's no warning.

Step 4: Perform the unlock action, the drone motors will start one by one, then slowly push up the throttle stick to take off.

Step 5: The drone remains at its current altitude and hovers after the throttle lever is centered, as shown in Figure 2-5.

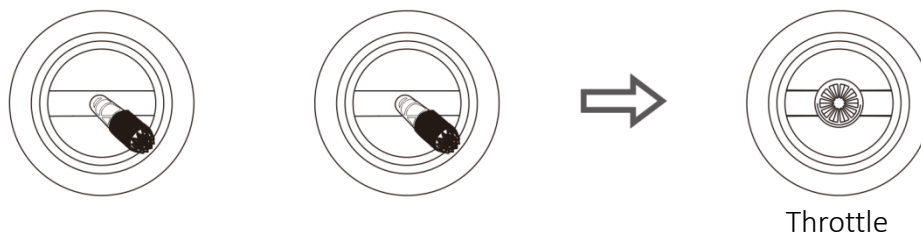


Figure 2-5 Unlock and take off

2.3.3.2. Land

Step 1: Slowly pull down the throttle stick, and the drone lands on the ground.

Step 2: After the drone lands, place the throttle stick to the down position, and then perform the locking action as shown in Figure 2-6.

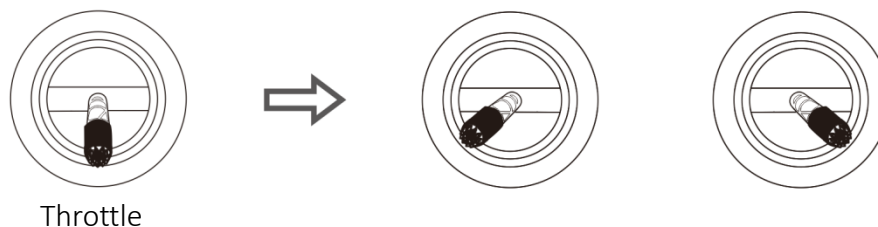


Figure 2-6 Land and Lock

Notes:

1. For the first test flight, the flight altitude shall not exceed 4m.
2. Do not fly beyond the visual range for the first test flight.
3. If there is light flashing showing an alert or there is a warning on the interface of the Agriculture Assistant APP during the flight, please land immediately and check the drone according to the plant protection assistant warning information.


2.3.4. GPS Operating Mode

2.3.4.1. Introduction


GPS operation mode has the features of being easy-to-use and quick-to-start, which is suitable for the operation in small, irregular and complex fields. In GPS mode, the

maximum flying speed of the drone is 10m/s. The spraying speed of the liquid is related to the flying speed. The faster the drone flies, the greater the flow rate is. When the drone hovers, the flow shuts down automatically.

2.3.4.2. Operating Procedure

Step 1: Before taking off, click “” button to start the testing spray, to check if there is air in the pipeline.

Step 2: The drone takes off and flies to the field for operation.

Step 3: Press the spray button “”, and fly the drone to the field and start the operation.

Notes: During the operation, make sure that the drone is in the visual range.

2.3.5. Autonomous Operation Mode

2.3.5.1. Introduction

Users can utilize the Agriculture Assistant app's field planning system for measuring fields, marking obstacles, and setting border points. The app automatically calculates and generates the optimal flight path. This mode is suitable for large or irregular fields. The fully autonomous operation route is illustrated in Figure 2-8. In the figure, the dashed line represents the operation interval, which can be set in the Agriculture Assistant app.

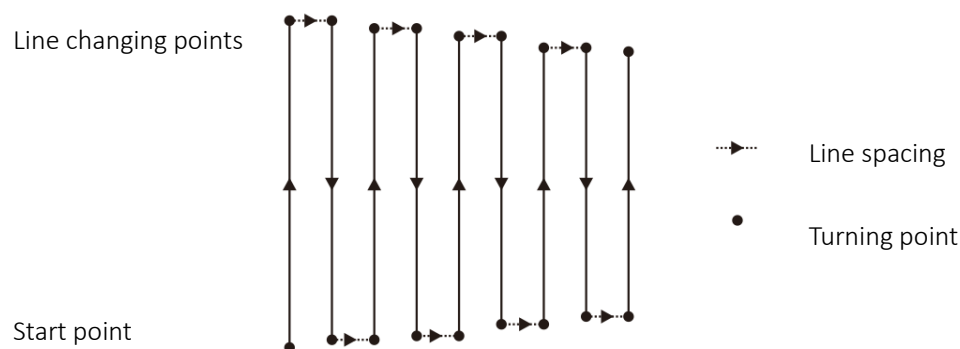


Figure 2-8 Auto Operation Route

2.3.5.2. Field Mapping Steps

Step 1: Run the Agriculture Assistant APP and there will be three options (GPS mapping mode, drone mapping mode and RTK hand-held marker mapping mode), you can choose according to the actual situation.

Step 2: Set a name for the field.

Step 3: Mark the border points: select the points at each corner of the borderline.

Step 4: Mark the obstacle: if there are obstacles in the field, click the obstacle point and select the shape. Click on the turning points of the obstacle shape to set it as an

obstacle point, and then click "OK" after the obstacle points setting is completed.

Step 5: Calibration point settings: after editing the operation area, calibration points need to be added. Calibration points are used for map rectification. When setting calibration points, make sure the reference object is easy to identify; the surrounding area is clear and suitable for the drone to take off. The operation area setting is completed when the calibration point is set.

2.3.5.3. Autonomous Operation Steps

Step 1: After the Agriculture Assistant APP is connected to the drone, click to expand the land/task list in the main interface.

Step 2: Select a field (or a field in the task list) and click to use the field.

Step 3: Place the drone at the calibration point of the operation area, click on "Calibrate", then click "Calibrate Drone Position".

Step 4: After the field is chosen, set the following parameters one by one: route angle, turning mode, route inner contraction, obstacle point spacing, altitude, usage per mu, ways of bypassing obstacle area.

Step 5: According to the route condition, select the routes ready to be sprayed (all routes are selected by default).

Step 6: Click "Start Operation" on the operation interface.

Step 7: Slide to unlock (please set the RTH height and take off height), and the drone will take off automatically and execute the planned route.

Step 8: Complete the operation (also can be finished manually during operation) and then generate the operation report.

Notes:

1. During the operation, it is necessary to ensure that the drone is in the visual range.
2. During the operation, the throttle stick of the RC can be toggled to adjust the flight altitude according to the plant condition. When the throttle stick is in the central position, the drone will resume its setting altitude.

2.4. Function Introduction

2.4.1. Remaining Liquid

2.4.1.1. Introduction

3WWDZ-U30B is equipped with a weight sensor, from which we can reckon the remaining liquid in real-time and display it, as shown in the figure below. During operation, users can choose the best breakpoints considering the remaining liquid and route length, which will improve the operation efficiency.

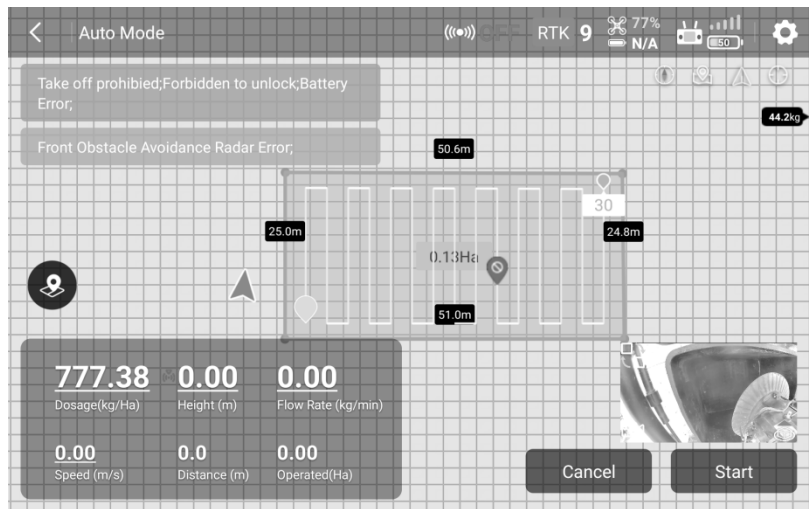


Figure 2-7

2.4.2. Resume Operation From The Breakpoint

2.4.2.1. Introduction

If the breakpoint is recorded during the operation due to running out of agrochemical, low battery, manual braking, obstacle avoidance, etc., the drone can be set to resume operation from the breakpoint following the established route.

2.4.2.2. Record the Breakpoint

During the operation, the drone will record the breakpoint and resume the operation at the breakpoint in the following situations:

1. Insufficient liquid in the tank.
2. When the low voltage protection function is enabled and the Level II warning is triggered.
3. Pitch or roll stick on the RC is pulled/pushed.
4. When the drone enters the RTH mode.
5. When the drone has obstacle avoidance radar and has detected the obstacle, which leads to an automatic brake.
6. When the location signal or heading signal is weak, the drone will automatically exit the operation mode and enter the protection mode, and record the current coordinate as the breakpoint.

Notes:

1. Any condition above is met, the drone will update the breakpoint.
2. The following actions can be set for the drone according to the operating environment after no remaining liquid: hover, climb up by 2m and hover, RTH or no action.

2.4.2.3. Return to The Breakpoint

The steps for returning to the breakpoint are as follows:

Step 1: Hover the drone manually in any open place and ensure there is no obstacle between this position and the breakpoint.

Step 2: Click "Return to the breakpoint " (click the **AB** Button or return to the Projection Point) in the Agriculture Assistant APP.

Step 3: The drone automatically rises or descends to the operating altitude and returns to the breakpoint.

Step 4: Resume the set route and continue the operation.

Notes:

For more detailed operation, please refer to the "User Manual of Agriculture Assistant APP".

2.4.2.4. Return to The Projection Point

If there is any obstacle on the way back to the breakpoint, you can choose "Projection Point" to return to avoid the obstacle.

Step 1: After the operation is paused, you can fly the drone manually to bypass the obstacle.

Step 2: Click "Continue" at the bottom right corner and select "Fly to Projection Point", and you will see options 1, 2, 3 corresponding to waypoints marked 1, 2, 3 in the flight routes.

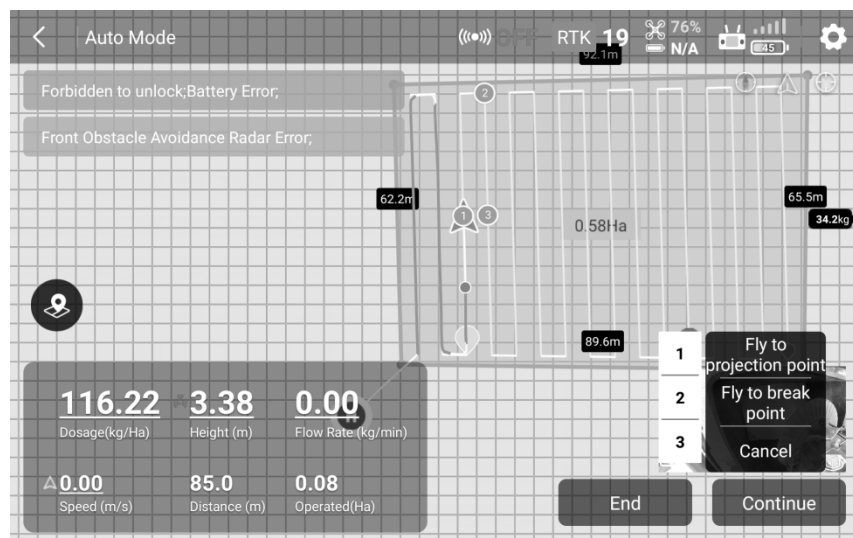


Figure 2-8

Step 3: Click on one of the points, and the drone will fly to the point to continue the operation.

2.4.3. Terrain-following Radar

2.4.3.1. Introduction



The working range of altitude stabilization function of the terrain-following radar is

between 1m and 10m. When the terrain-following radar is turned on, the relative height of the drone and the plants can be kept unchanged during the operation. The drone will fly following the terrain to ensure uniformity of the spraying.

2.4.3.2. Terrain Setting

For both plain and mountainous terrain, the drone adopts different tracking strategies and the user needs to set the simulated scene of the flight according to the actual operating terrain.

Setup procedure:

Step 1: Click  at the top right corner enter the setting page, then click  enter the radar setting interface.

Step 2: According to the terrain situation, select "plain" or "mountain" on the right side of the column "Terrain Settings".

Notes:

1. Radar module housing should not be crushed causing deformity.
2. Keep the radar antenna cover clean and wipe the surface regularly with a soft damp cloth depending on the frequency of use.
3. When flying the drone over an object surface with a slope, the correlation between simulated slope and flight speed is shown below: 10°(<2m/s), 6° (< 4m/s), and 3° (< 6m/s).

2.4.4. Low Battery Level Protection

The drone has a low battery level protection function. The user can set the warning threshold, which is the battery level in percentage in the Agriculture Assistant APP. When the value is reached, the drone will act according to the setting. The action can be set as: hover, land, return, no action (only light flashing).

2.4.4.1. Level I Protection

As the Level I protection, the drone indicators flash red. The protection will be triggered after the indicators flash for 10s. The factory default Level I low power threshold is 30%, and the protective action is "no action". At the same time, the Agriculture Assistant APP sends voice notification "Level I Low Battery".

2.4.4.2. Level II Protection

As the Level II protection, the drone indicators flash red. The protection will be triggered after the indicators flash for 10s. The factory default Level II low power threshold is 10%, and the protective action is "auto-landing". At the same time, the Agriculture Assistant APP sends voice notification "Level II Low Battery".

Notes:

1. When Level I warning occurs, fly the drone to the safe area and land as soon as possible.

2. It is necessary to avoid the Level II warning as much as possible to avoid accidents.
3. After the low battery protection action is triggered, the drone can only be switched to Gesture mode or RTH mode.
4. When the drone lands automatically, the protection mode can be quit by switching to Gesture Mode.

2.4.5. Lost Control Protection


2.4.5.1. Overview of Return to Home(RTH) Mode

When the GPS signal reaches the seven satellites for the first time during taking-off or flight and the signal quality is good, the drone will record the current location as the RTH point. The process of the drone returning automatically to the RTH point is called RTH.

2.4.5.2. Protection Logic

When the drone is in good GNSS signal, the compass work normally, and the RTH point has been successfully recorded. If the RC signal is lost for any reason during the operation, the protection action will be triggered. The protection actions include landing, hovering and RTH.

Notes:

1. When the RC is well connected, RTH can be canceled by toggling the RC switch to "S", and the drone can be controlled manually.
2. When the RC is well connected, RTH can be canceled by long-pressing the “” button for 2s.

2.4.6. Obstacle Avoidance System

The drone is equipped with a new millimeter wave radar for obstacle detection, which is unaffected by ambient light and dust. When the working conditions are met, the radar can detect the obstacles in front of and behind the drone. The maximum detection distance can be up to 40m. When obstacles are detected, the drone self-brake to ensure safety during the operation. The obstacle avoidance function is enabled by default and can be turned off in the Agriculture Assistant APP.

2.4.6.1. Detection Range

The detection range of the radar module is as follows: $\pm 60^\circ$ in the vertical direction, as shown in Figure 2-11, and $\pm 30^\circ$ in the horizontal direction, as shown in Figure 2-12. If an obstacle is outside this detection range, the radar module will not be able to detect it. In such cases, please fly with caution.

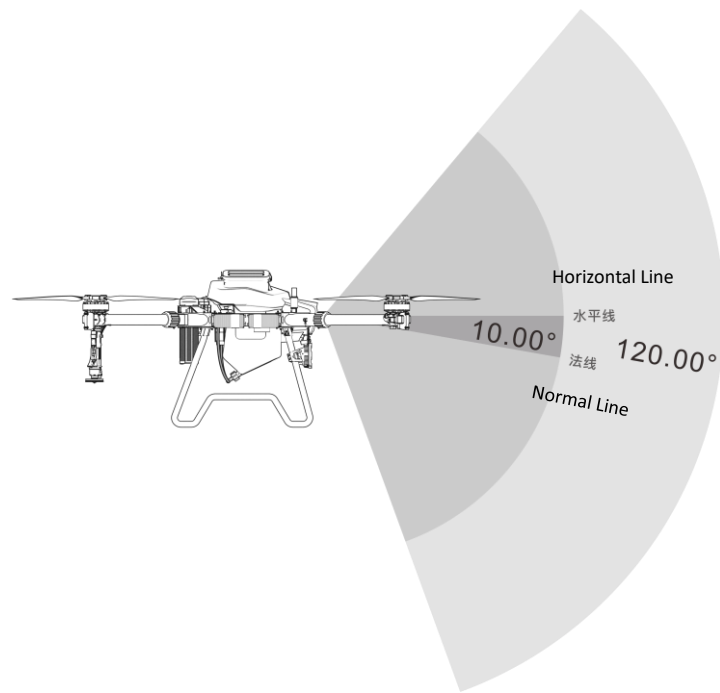


Figure 2-9 Vertical View

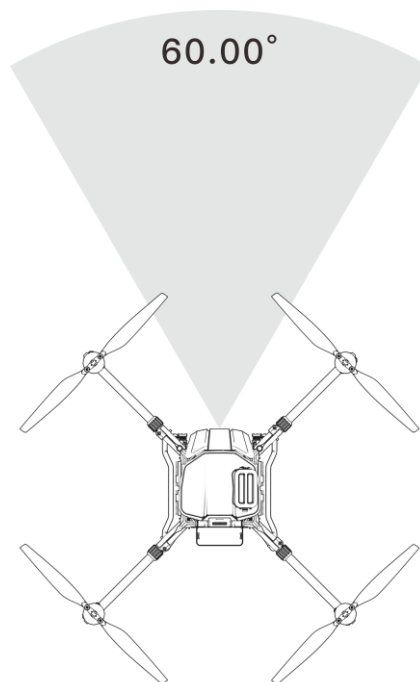
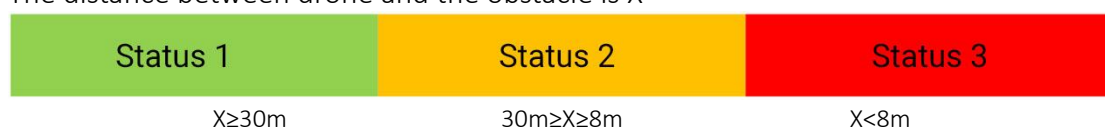


Figure 2-10 Horizontal View

2.4.6.2. Safety Braking System

The distance between drone and the obstacle is X



Status 1: When the obstacle distance $\geq 30m$, the drone will not brake and the APP will

not display any warning.

Status 2: Entering the yellow warning zone, the drone slows down to 2m/s and maintain it. The APP will show the distance between the drone and the obstacle in the yellow zone.

Status 3: Entering the red warning zone, the drone will brake urgently and enter the Safe Mode. In the Safe Mode, the drone will remain to hover and cannot be operated to fly towards the direction of the obstacle. The APP will display the obstacle distance in the red zone. Flying the drone to the opposite direction of the obstacle will exit the safe mode.

Special Condition:

If any obstacle appears suddenly during the flight, the drone will stop with maximum braking force.

2.4.6.3. Obstacle Circumvent

Equipped with an industry-leading vehicle-level radar, the 3WWDZ-U30B agricultural drone possesses excellent spatial awareness. When obstacles are detected in the forward or backward flight direction, it can autonomously plan a path to bypass the obstacle from the left or right without the need for manual intervention.

To activate this feature: Open the "Obstacle Circumvent" on the "Radar Setting" page (default closed) in the Agriculture Assistant APP.

2.4.6.4. Notification

1. When the obstacle avoidance function is turned on, the obstacle function will not be activated if the drone is in "S" flight mode or the drone is landing.
2. After the obstacle avoidance function is turned on, to ensure sufficient braking distance, the maximum flying speed is 13.8m/s.
3. The obstacles can not be detected when the vertical FOV is greater than 15° or less than -15°.
4. The obstacle avoidance function will not be activated during taking-off, landing or line changing.
5. When the obstacle disappears, the drone will be in the protection mode for 2s, after which it will gradually lift the speed limit.

2.4.6.5. Description of Typical Obstacle Avoidance Scenarios

Trees, Poles: obstacle avoidance radar can detect the obstacle within 25m, and continuously show warning with the distance. When the distance is less than 30m, the drone will brake automatically to ensure safety.

Wires: Taking the 1.5cm-diameter wire as an example, as the reflection of the wire is poor, the radar is able to detect the wire 13m away while the drone is flying right towards the wire at a speed of 3m/s. The thinner the wire or the higher the flight speed is, the poorer the obstacle avoidance effect will be.

Notes:

1. When using the radar module, follow the local radio regulations and legal

requirements.

2. For obstacles of different sizes and materials, the effective working range of the radar module will vary. For example, when detecting pedestrian, power cables, dry branches or conifers, the effective detection distance will decrease. Please operate carefully.
3. Radar modules are suitable for flat terrain and may cause false alarms when the slop angle is large.
4. When the surface beneath the drone is less than 1.5m, it is prone to cause false alarms.
5. Never disassemble the radar module by yourself. Otherwise, the improper installation might cause malfunction of the radar.
6. Do not crush or squeeze the housing of the radar module.
7. Radar modules can be used normally on rainy days, and radar detection performance might decrease by 10-20%.

3. Maintenance and Common Troubleshooting

3.1. RC Maintenance & Troubleshooting

- The RC needs to be wiped regularly to keep it clean. Keep the RC from water, agrochemical and dust.
- Please fold the antenna after use to avoid damage.
- If the drone cannot hover and keeps flying in one direction when the control stick is at the neutral position, the control stick of the RC needs to be calibrated.
- If other issues occur, please follow the instructions provided by the app's self-check system or contact the corresponding technical personnel.

3.2. Drone Maintenance & Troubleshooting

- Delicate electronic components are inside the drone. Do not soak the drone in water when cleaning.
- Regular inspection of components is required. Make sure the screws are fastened at all the joints.
- During transportation, make sure to properly fold the arms so that the motor base is placed on the folding structure.
- If the structural parts (such as frames, arms, landing gears) are damaged, please contact the after-sales service for replacement.
- If other issues occur, please follow the instructions provided by the app's self-check system or contact the corresponding technical personnel.

3.3. Motor Maintenance & Troubleshooting

The working environment of agricultural plant protection drones' motor is harsh. Water mist, liquid and agrochemical residue are the main factors causing damage. Therefore, it is necessary to:

- Clean the housing of the motor with a warm cloth after the operation. Remove the residue on the surface, and do not flush the inside of the motor with high-pressure water. Prevent water from leaking into the motor, which will shorten the service life.
- Check the motor regularly. When the resistance of the motor is high, the sound is abnormal or the gap between the motor and the motor base becomes large, please contact after-sales immediately and maintain according to the instructions by the after-sales.
- If other issues occur, please follow the instructions provided by the app's self-check system or contact the corresponding technical personnel.

3.4. Propeller Maintenance & Troubleshooting

- If the propeller cracks or is damaged, please replace it in time. Otherwise, it will not have enough lifting power and the drone will be unstable, which will cause safety problems.
- Pay attention to the marking on the propellers when installing them. Motor No.1 and No.3 should match "CCW" propellers, and motor No.2 and No.4 should match "CW" propellers.
- Clean up agrochemical residues after finishing the operation.
- Insert the propeller into the propeller holder during transportation.
- If other issues occur, please follow the instructions provided by the app's self-check system or contact the corresponding technical personnel.

3.5. Battery Maintenance & Troubleshooting

3.5.1. UPS

This model is equipped with a built-in backup battery that allows the flight control system to remain operational for 5 minutes after the main power batteries are disconnected, effectively preventing delays caused by flight controller reboot and GNSS satellite acquisition.

3.5.1.1. Specification Parameters

No.	Project	Specification Parameters
1	Cell Type	Rechargeable Lithium-Ion Battery
2	Individual Cell Voltage	3.7V
3	Capacity	2500mAh
4	Discharge	-20°C - 55°C

5	Charge	0°C - 45°C
6	Storage (Within 3 Months)	-5°C - 35°C

3.5.1.2. Notes

- When the agricultural drone is not used for a period of time, please connect the drone to the battery once a month for no less than 20min, in order to prevent the battery from discharging.
- Do not disassemble the battery.
- It is strictly forbidden to throw the battery into the fire, otherwise, it may explode.
- Batteries should not be immersed in liquids such as freshwater, seawater, beverages, etc.
- Using damaged batteries are prohibited.

3.5.2. Battery

- Charge in the normal charging mode regularly to balance the battery voltage.
- Avoid charging at a temperature of above 45 °C.
- If the battery falls from height, it might cause a short circuit or even combustion.
- Make sure the battery is firmly connected to the drone, otherwise it may affect the performance of the drone.
- If corrosion or discoloration is found in the battery plug of the drone, wipe it with absolute alcohol in time and contact the after-sales department and follow the instructions.
- Do not use batteries which have dents, scratches and deformation on the surface. Serious mechanical damage may lead to the risk of short circuits or combustion.
- Make sure all wires are not damaged. Severely damaged wires may cause short circuits or combustion.

Storage Instructions:

- For storage of a large number of batteries, it is recommended to keep 30cm between each storage unit.
- Please avoid direct sunlight for more than 10min under any storage condition.
- Battery storage environment should be maintained at room temperature (15°C - 35°C). Long-term storage above 35°C will accelerate the aging of the battery. Long-term storage at 0°C - 15°C may shorten the service time, but after several times of use at room temperature, the normal condition can be restored.
- Battery storage should avoid a humid environment. Keep storage environment dry and not ventilated.
- Battery storage locations should not be places where large items are often moved in and out to prevent accidental collisions.

Transportation Instruction:

- It is recommended to use a temperature-resistant or flame-retardant box with a cover to store batteries. It is recommended to use the shockproof and tilt-proof sponge in the original box in other packages.
- Avoid putting the charging and discharging cables on the edge of the box to prevent accidentally being crushed, otherwise, it will lead to a short circuit when being used.
- During the operation, if the batteries are placed in a vehicle, ventilation should be guaranteed and avoid direct sunlight. The place exposed to direct sunlight in a sealed vehicle may have a temperature of above 80°C, which may cause the battery to burn.

Emergency Instructions:

Adequate sand, fire extinguishers, and heat-insulating gloves should be prepared in places where batteries are stored, transported, or used.

When smoking and burning of batteries are found, the following measures should be taken immediately:

1. Battery is just starting to smoke (or has a burnt odor): Determine the part where a short circuit happens immediately. Lift the battery handle or charge-discharge cable (with heat-insulating gloves if necessary) and quickly drag the battery into the open room or outdoor. Completely bury the whole battery with sand (the charge-discharge cable needs to be buried in if there is smoking). Be careful to wait until the battery has completely cooled down before taking it out (otherwise the battery may continue to smoke).
2. Batteries emit heavy smoke: immediately use sand and fire extinguishers to extinguish or bury the burning batteries while relocate the surrounding batteries and other flammable objects. If the surrounding flammable and explosive objects (liquids) cannot be removed, immediately use large quantities of water for rapid fire extinguishing and cooling.
3. Batteries are on fire: immediately use a large amount of water, fire extinguishers and sands to extinguish the fire (disconnect the power supply of surrounding electrical equipment first) while removing the surrounding batteries and other flammable material.

Notes:

When using fire fighting equipment to extinguish fire, strictly follow the requirements and specifications of the local Fire Fighting authorities.

3.6. Plug Maintenance & Troubleshooting

- The plug must be inserted completely when it is connected, otherwise, it will heat the plug and affect flight.
- The power plug and battery plug should be replaced if they have turned black or sparked.

3.7. Spray System Maintenance & Troubleshooting

- Fill the water tank, pipe and nozzle with clean water to clean them when the operation is finished.
- Avoid mixing herbicides and pesticides, otherwise, it will be harmful to plants.
- In the case of long-term storage or transportation of the drone, always empty the tank.
- It is forbidden to run the water pump at high speed on an empty tank for long time.
- Avoid using powders and high-concentration emulsifiers to avoid blocking the spray pipe.
- If other issues occur, please follow the instructions provided by the app's self-check system or contact the corresponding technical personnel.

4. Transportation Instructions

Packaging method:

The drone will be placed in the package box with flexible supporting material embedded in the package box while shipping.

Package Size: 903mm*863mm*763mm as shown below.

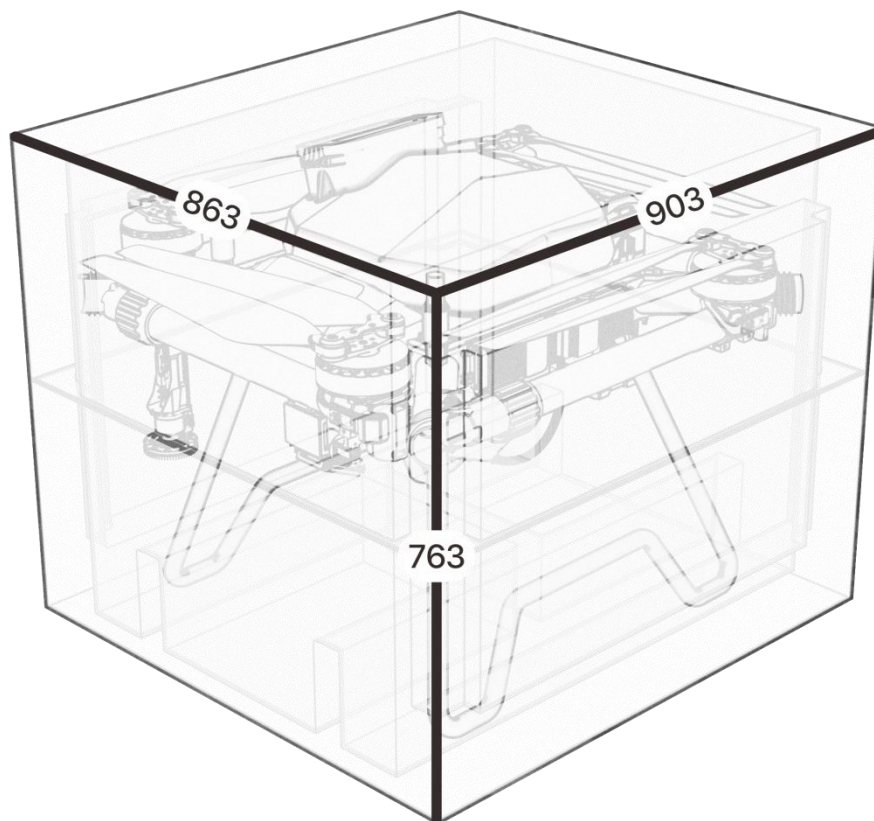


Figure 4-1

5. Hazards and Safety Checklist and Countermeasures

No.	Hazard	Countermeasures
1	Foldable Structure	When folding or unfolding the drone, be aware of the hand pinch hazard sign and keep your fingers away from the folding structure.
2	High-speed Rotating Propeller	Keep a safe distance from the drone and keep it away from people, animals or other obstacles during operation.
3	Charger While Being Charged	Place in a dedicated charging area and environment. Ensure good ventilation. When the charger is connected to power, make sure the charger is grounded.
4	Tank	Flush it with clean water after use and cover it with the lid, and store in a safe place.
5	Battery	The maximum voltage is up to 51.8V. Please use in strict accordance with the relevant safety regulations and the instructions of the battery, and pay attention to safety.
6	Agrochemical	When handling agrochemical, pay attention to the risk of different kinds of agrochemical. Fully understand the using methods in advance.
7	During the Operation	Do not operate in bad weather, such as strong wind (wind speed 8m/s or above), heavy rain (rainfall 25 mm/12 hours or above), snow, fog, etc.

6. Manufacturer Information

Manufacturer: Topxgun (Nanjing) Robotics Co., Ltd.

Address: No.8 Building, Jiangsu Software Park, No.1 Dongji Avenue, Jiangning District, Nanjing, China

Email: sales.global@topxgun.com

Website: www.topxgunag.com

7. Appendix

7.1. Specification Parameters

Specification	Parameter
Package	
Package Size	903mm*863mm*763mm
Net Weight	28.1kg

Gross Weight	42.1kg
Body Frame	
Symmetrical Motor Wheelbase	1915mm
Arm Length	705mm
Spraying Mode	
Dimension (Folded State)	894*894*718mm
Dimension (Unfolded State)	2438*1459*718mm (With unfolded propellers)
Dimension (Unfolded State)	1522*1522*718mm (Without propellers and nozzle, antenna included)
Spreading Mode	
Dimension (Folded State)	894*894*733mm
Dimension (Unfolded State)	2438*1459*733mm (With unfolded propellers)
Dimension (Unfolded State)	1522*1522*733mm (Without propellers and nozzle, antenna included)
Power Motor	
Model	X30
Stator Dimensions	111x18mm
KV	85 RPM/V
Power	6kW (Single motor)
Maximum Thrust	33kg (Single motor)
Number of Motors	4
Power ESC	
Rated Working Current	60A
Operating Voltage	53.2V (14S LiPo)
Signal Frequency	500Hz
Drive PWM Frequency	20kHz
Foldable Propeller	
Material	Nylon Carbon Fiber Composite Material
Diameter	43inch, 1090mm
Pitch	13.5inch
Weight	460g

Spraying System	
Tank	
Rated Capacity	30L
Weight	3.5kg (Including liquid pump and other accessories)
Pump	
Pump Type	Metering peristaltic pump
Number of Channels	2
Maximum Flow Rate	10L/min (Single pump)
Measurement Error	< 5%
Centrifugal Nozzle	
Rated Voltage	53.2V
Protection Level	IP67
Maximum Speed of Centrifugal Disc	10000rpm
Maximum Atomization Capacity	5L/min (Single nozzle)
Spray Range	5 - 8m
Recommended Spray Range	6m
Atomization Particle Size	30 - 500μm
Spreading System (Optional)	
Tank Capacity	45L
Maximum Payload	30kg
Weight	4kg (Including the tank, spreader and other components)
Feeding Mode	Ration by rolling feeder
Spreading Mode	Centrifugal spreading mode
Spread Range	5 - 10m
Recommended Operating Temperature	0°C - 40°C
Package Size	456*422*638mm
Radar System	
Terrain Following Radar	
Modulation Mode	FMCW

Waterproof Level	IP67
Height Range	1-20m
Range Accuracy	0.1m
Obstacle Avoidance Radar	
Detection Range	1-150m
Using Condition	Flight relative altitude >2m
Safe Distance	4m
Avoidance Direction	Front
Autonomous Obstacle Avoidance	Supported, autonomously avoids obstacles to the left or right.
Protection Level	IP67
FPV Camera	
FOV	Horizontal 86°, Vertical 52°
Resolution Ratio	Default 720P, max 1080P
Flight Parameter	
Drone Weight (With Battery)	34.1kg (Spraying mode) 35.1kg (Spreading mode)
Rated Take Off Weight	64.1kg (Spraying mode) 65.1kg (Spreading mode)
Maximum Take Off Weight	< 150kg
Hover Precision (GNSS signal properly)	Horizontal $\pm 1.0\text{m}$ Vertical $\pm 0.5\text{m}$
	Horizontal $\pm 10\text{cm}$ Vertical $\pm 10\text{cm}$ (RTK enabled)
	Vertical $\pm 0.1\text{m}$ (Radar enabled)
Hover Time*	≥ 5.5 min (Take-off weight 64.1kg & 20Ah battery) ≥ 14 min (Take-off weight 34.1kg & 20Ah battery)
*The hover time is measured near sea level, when the wind speed is less than 3m/s, and the ambient temperature is 25°C.	
Maximum Flight Speed	10m/s
Horizontal Distance Limit	1000m
Maximum Take-off Altitude	2000m
Recommended Operating Ambient Temperature	0 - 40°C
Flight Control System	
Model	TIA2025

Input Voltage	30 - 60.9V
Rated Power	20W (excluding radar, pump, and other peripherals)
Interface Type	CANBus, RS485, PWM, USB, etc.
Protection Level	IP67 (with external connectors secured)
Working Temperature	-10°C - 45°C
Remote Controller	
Model	TC2S
Operating Frequency	2.400-2.4833GHz
Signal Effective Distance (no interference, no obstruction)	Maximum communication distance: 10km; image transmission distance: 3km (plant protection environment)
RTK High Accuracy Mapping	Support
Mapping Accuracy	RTK enabled (fixed solution): Horizontal: $\pm 0.1\text{m}$; Vertical: $\pm 0.1\text{m}$
Screen Size	7 inch
Battery Voltage	3.7V (Rechargeable lithium battery)
Battery Capacity	20000mAh
Battery Life	6-8h
Weight	1120g
Size	280x195x101mm
GNSS System	
Frequency	BDS: B1/B2; GPS: L1/L2; GLONASS: L1/L2;
Hover Accuracy (RMS)	RTK not enabled: horizontal: $\pm 0.6\text{m}$, vertical $\pm 0.3\text{m}$
	RTK enabled (fixed solution): horizontal: $\pm 0.1\text{m}$, vertical: $\pm 0.1\text{m}$
Orientation Accuracy (RMS)	0.4°
Charger (TC4501P)	
Input Power	AC 100V - 240V
Input Voltage Frequency	50/60Hz
Output Power	DC 60.9V (Max)
Output Current	83A (Max)
Output Power	4500W (Max)

Channel	Single Channel
Net Weight	11.8kg
Gross Weight	12.2kg
Size	305*238*377mm
Battery (TB1420S)	
Voltage	52.5V
Capacity	20000mAh
Discharge Rate	8C
Charge Rate	5C
Protection Level	IP56 (With batteries installed to the drone)
Battery Life Time	1000 cycles (Capacity will be attenuated, no limit to use)
Weight	8.0kg (With 2 batteries installed during flight)
Battery (ZAB1420-03)	
Voltage	53.2V
Capacity	20000mAh
Discharge Rate	10C
Charge Rate	5C
Protection Level	IP56 (With batteries installed to the drone)
Battery Life Time	1000 cycles (Capacity will be attenuated, no limit to use)
Weight	8.0kg (With 2 batteries installed during flight)
Size	139*240*316mm
Battery (ZAB1420-01)	
Voltage	53.2V
Capacity	20000mAh
Discharge Rate	8C
Charge Rate	4C
Protection Level	IP56 (With batteries installed to the drone)
Battery Life Time	1000 cycles (Capacity will be attenuated, no limit to use)
Weight	8.0kg (With 2 batteries installed during flight)

Size	139*240*316mm
------	---------------